

# Timed Data: Are deadlines enough?

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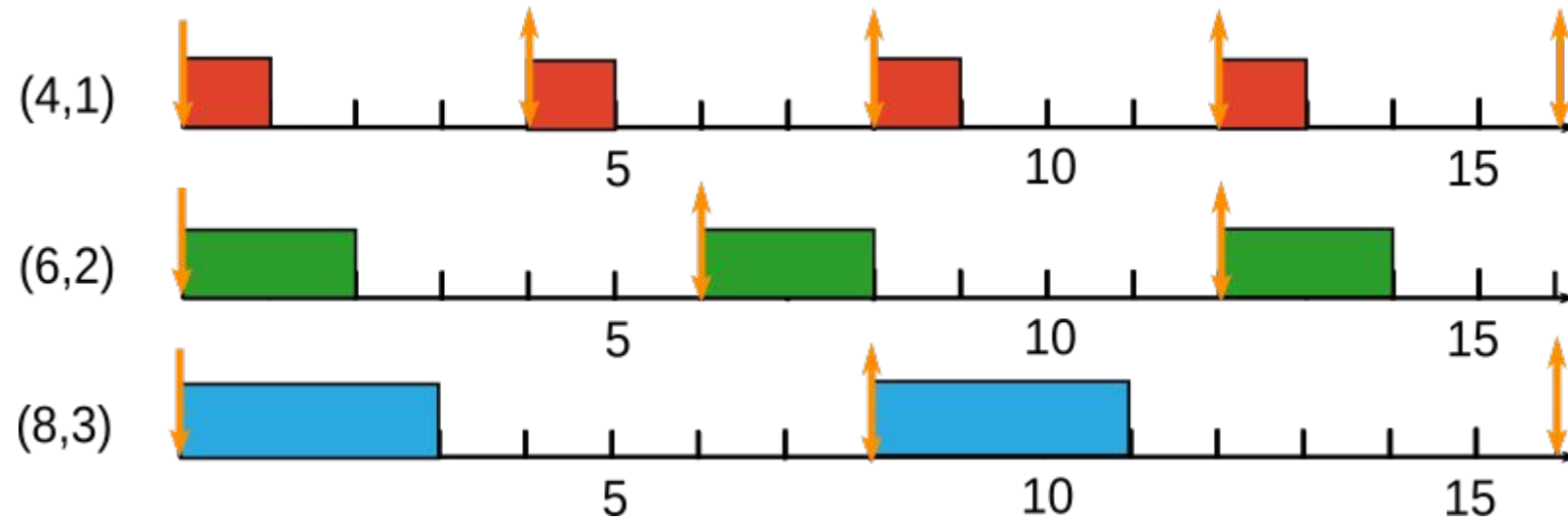
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**UFSC**

**Prof. Paolo Milazzo**

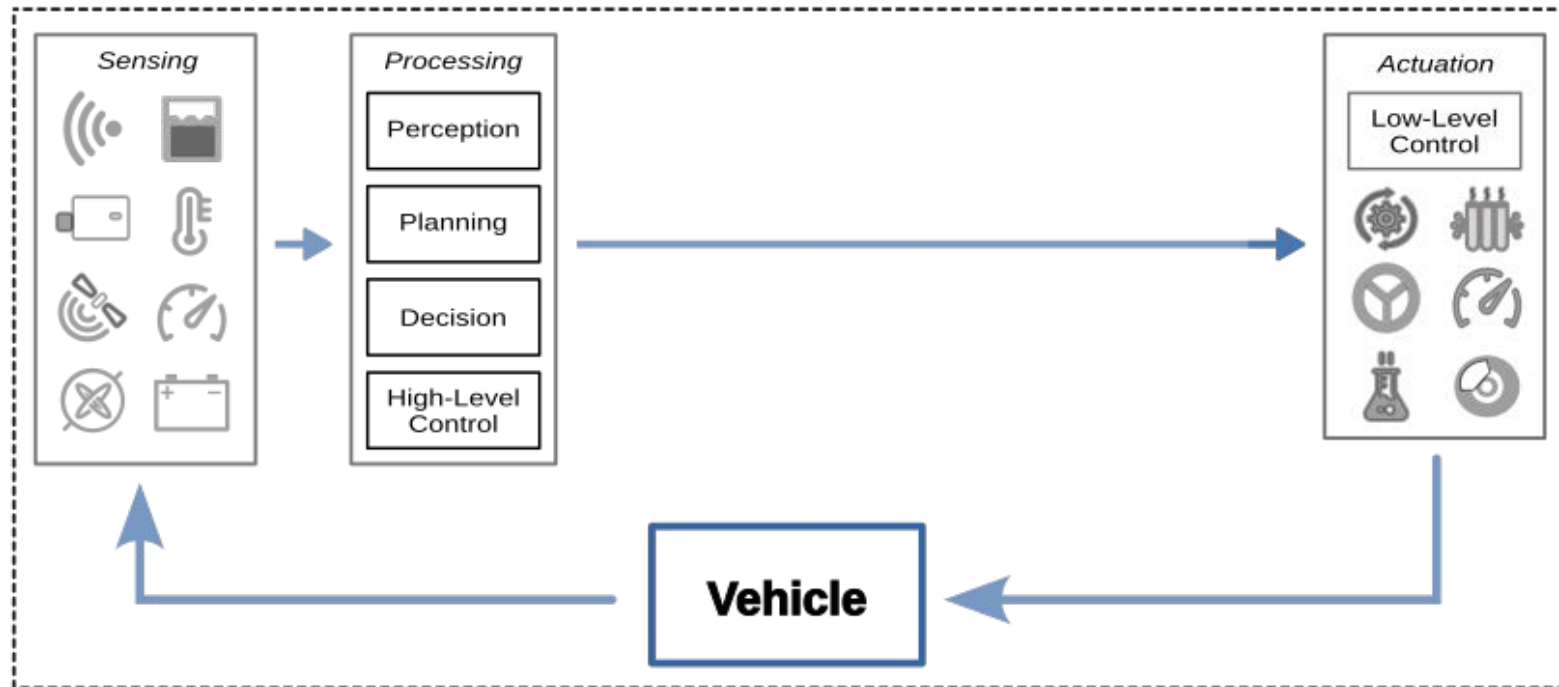
**UniPi**

# The complexity of S-o-t-A Real-Time Systems



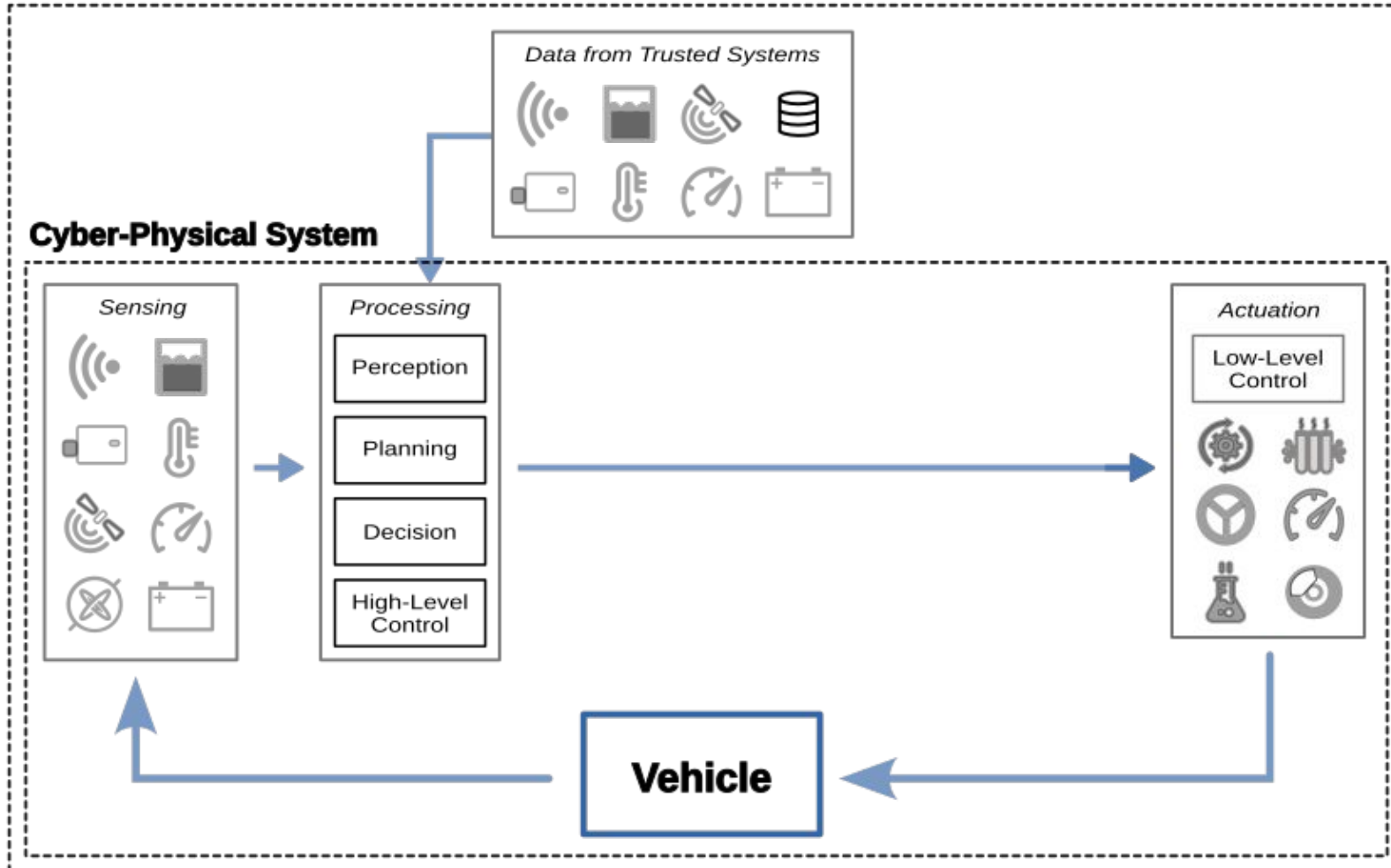
# The complexity of S-o-t-A Real-Time Systems

## Cyber-Physical System



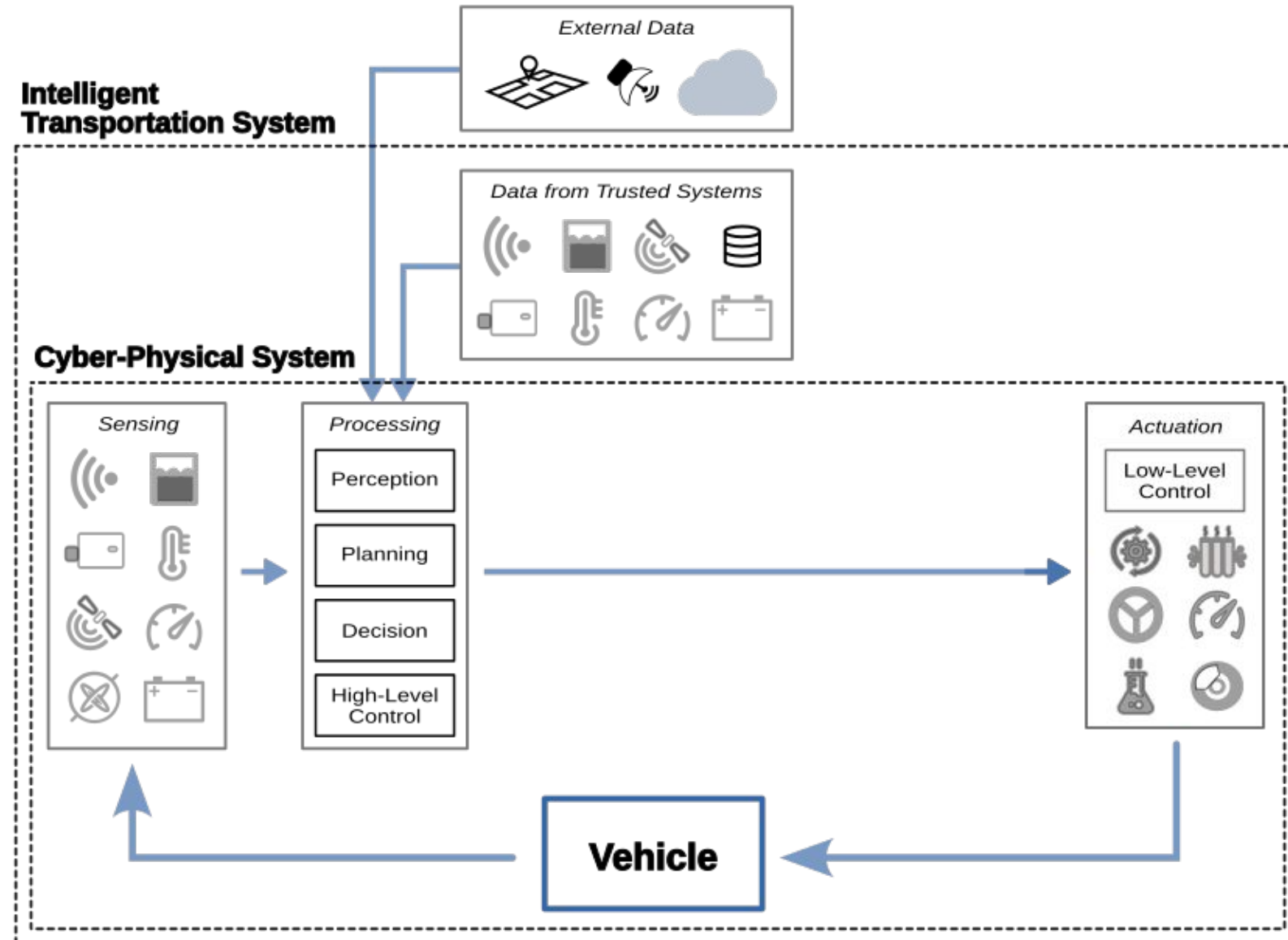
# The complexity of S-o-t-A Real-Time Systems

## Intelligent Transportation System



# The complexity of S-o-t-A Real-Time Systems

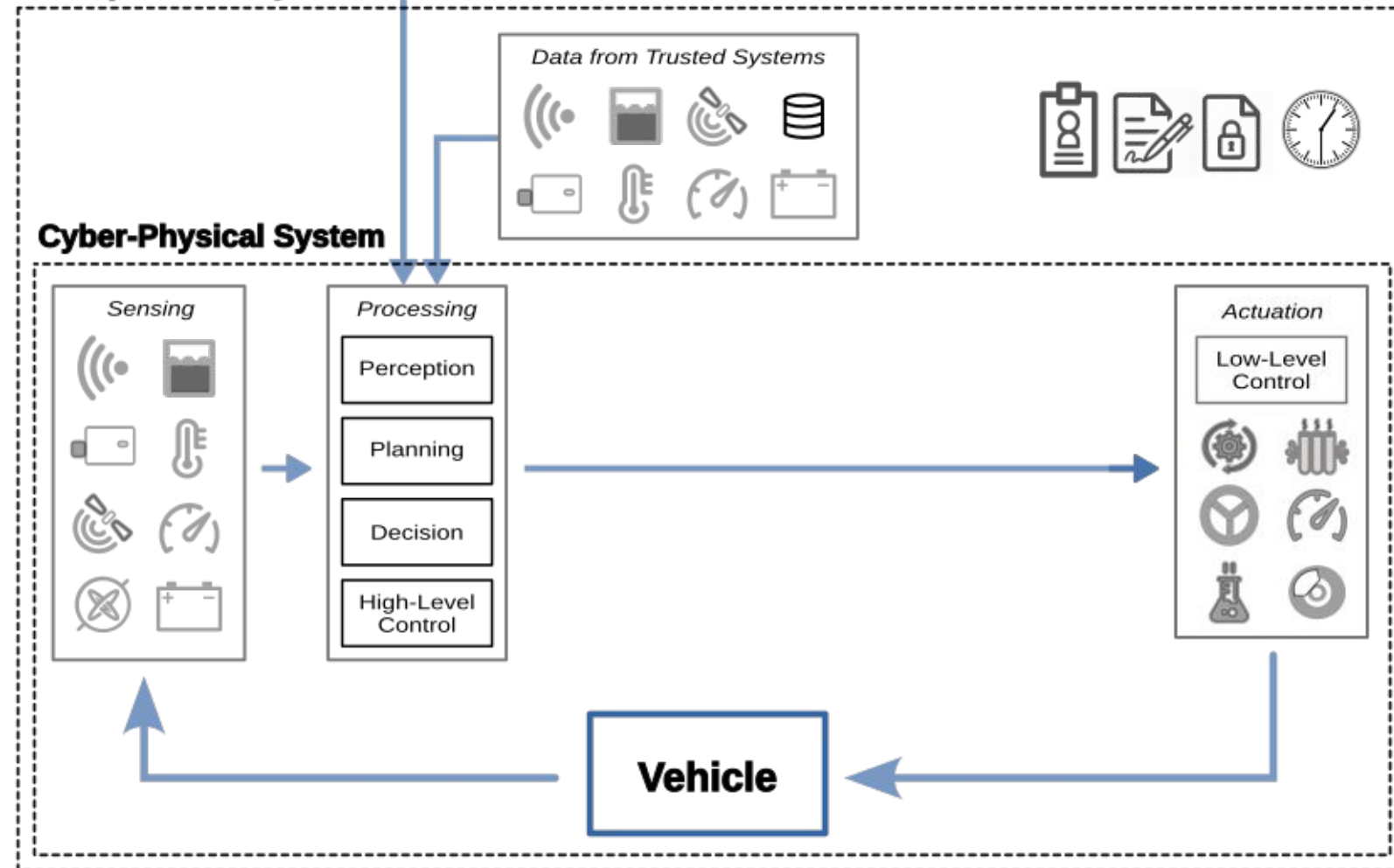
Cloud



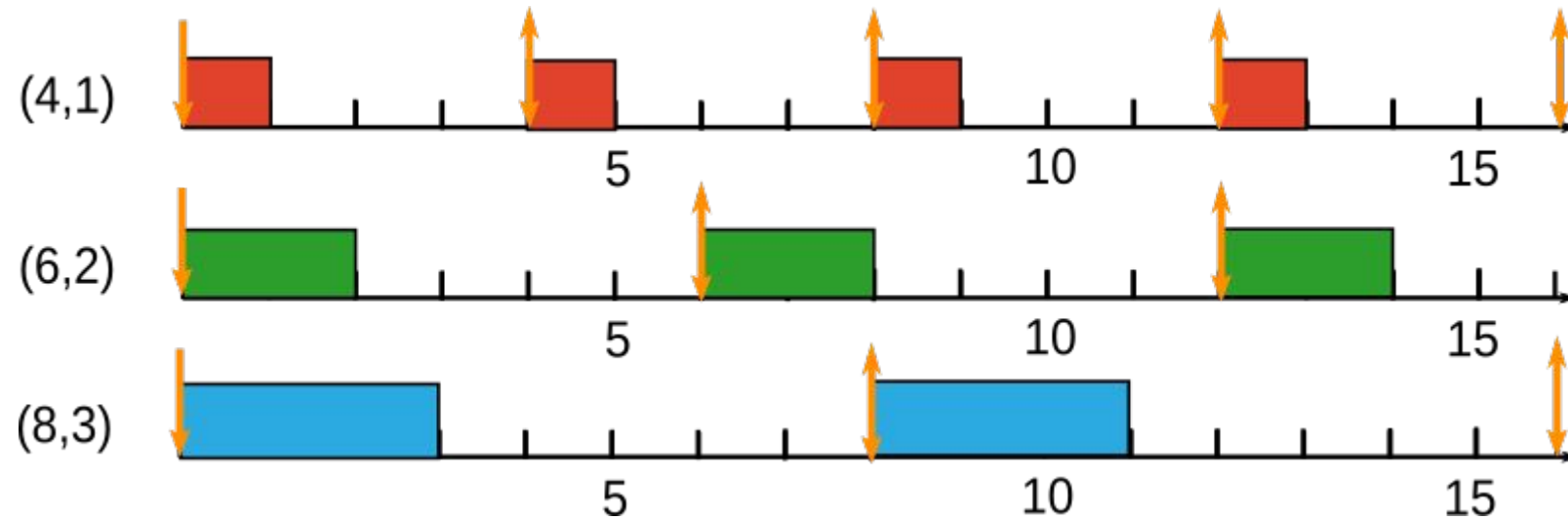
# The complexity of S-o-t-A Real-Time Systems

Cloud

Intelligent Transportation System



# What is lacking from classical RT Theory?

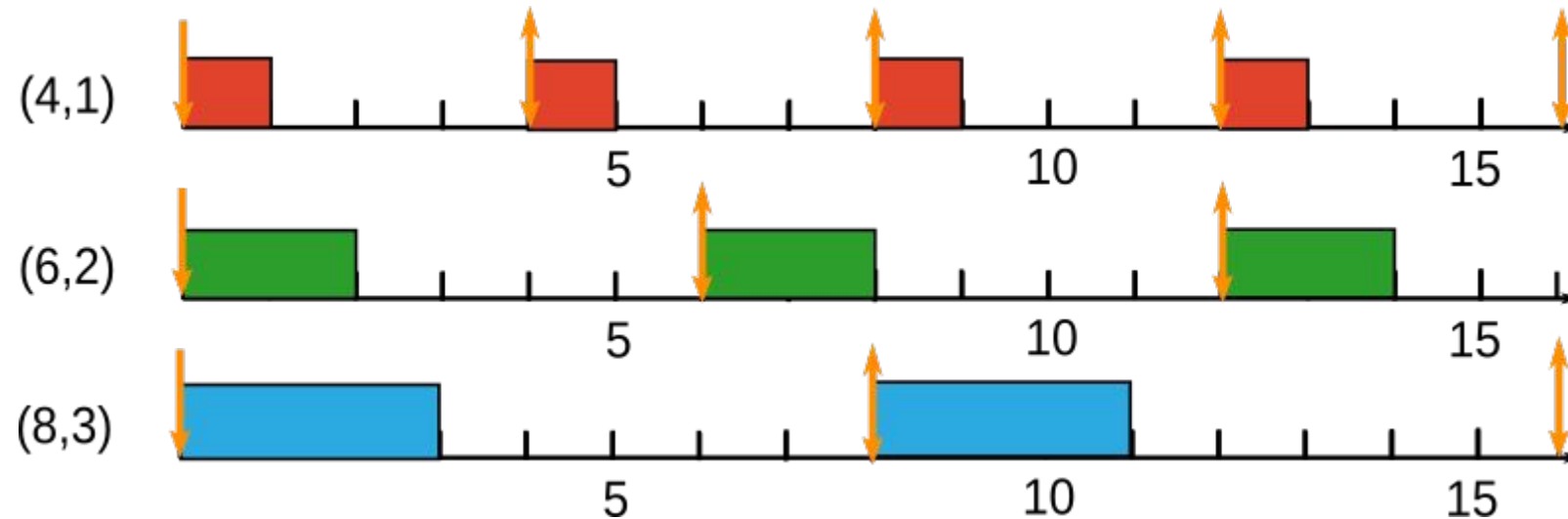


# What is lacking from classical RT Theory?

Contention?



- Multicores
- OS Strategies
  - $\mu$ -kernels
  - Isolation
  - Page Coloring
  - Monitoring + ML-Scheduling
- Safety-Critical: WCET estimation
  - Over- or Sub-estimated?





# What is lacking from classical RT Theory?

Contention?



Data?



Timed

- What? When? Where?
  - Semantics
  - Fault-Tolerance
    - Fault tracing?
    - Replication?
- Safety-Critical:
  - **Data quality?**
  - **Data Expiration?**

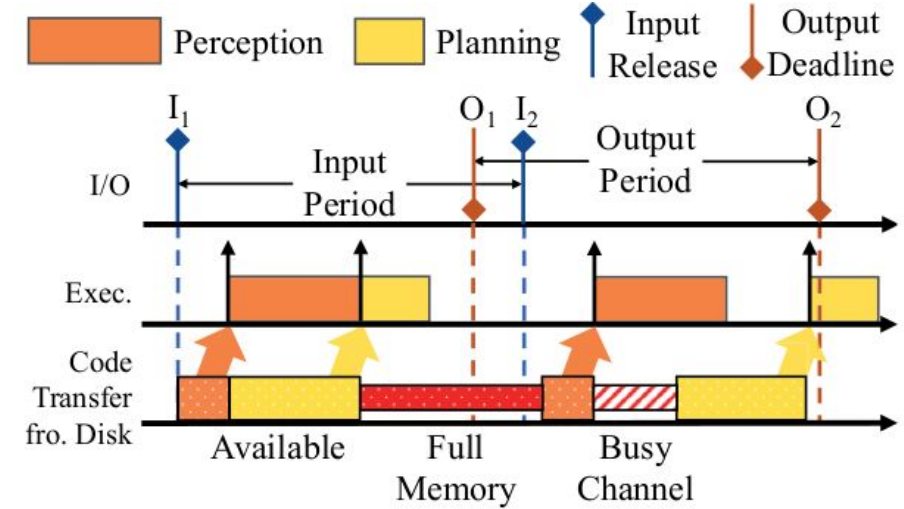
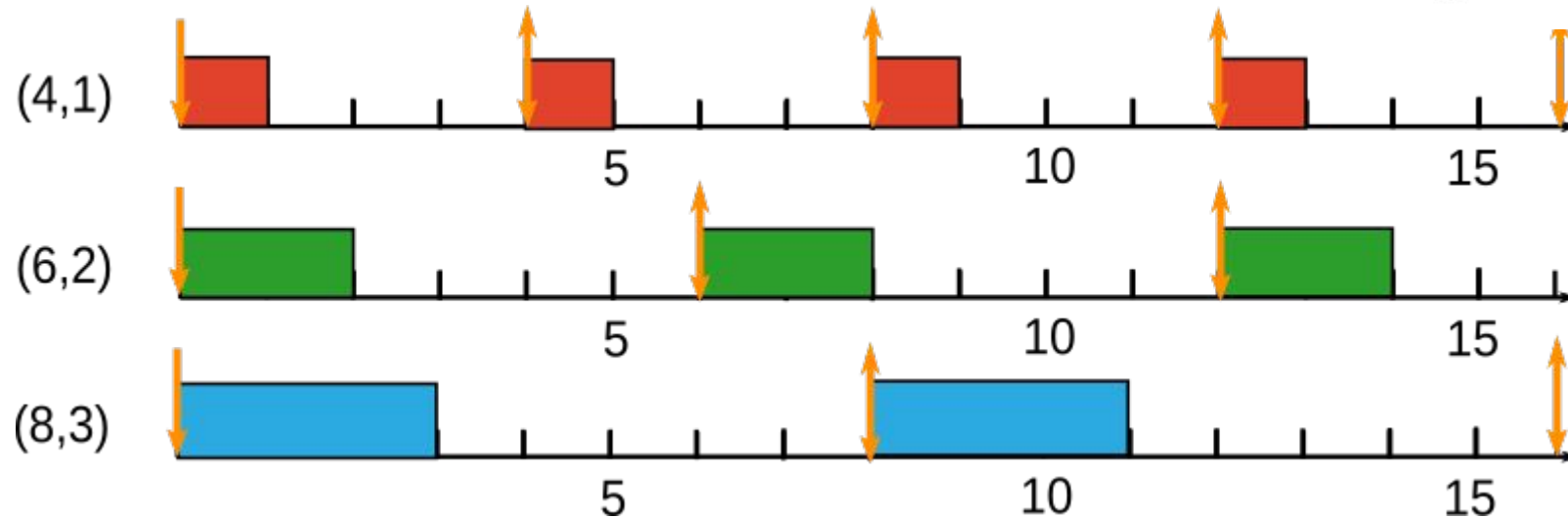


Fig. 1: Autoware with periodic input.



# What is lacking from classical RT Theory?

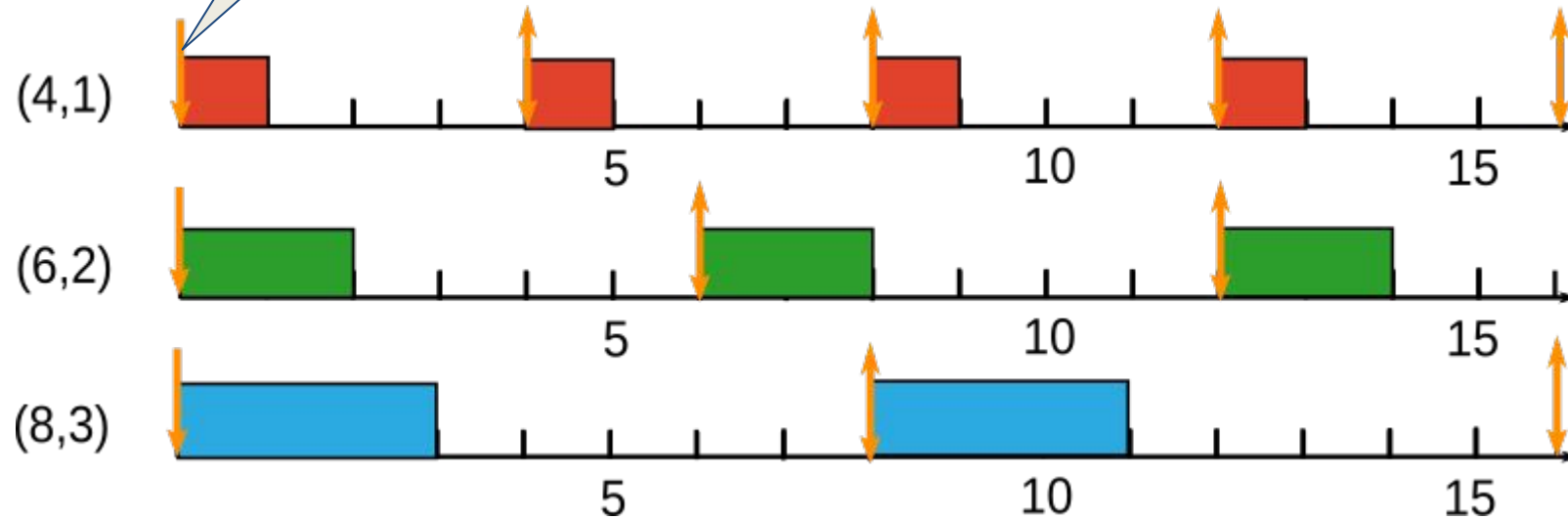
Contention?

Data?



Timed

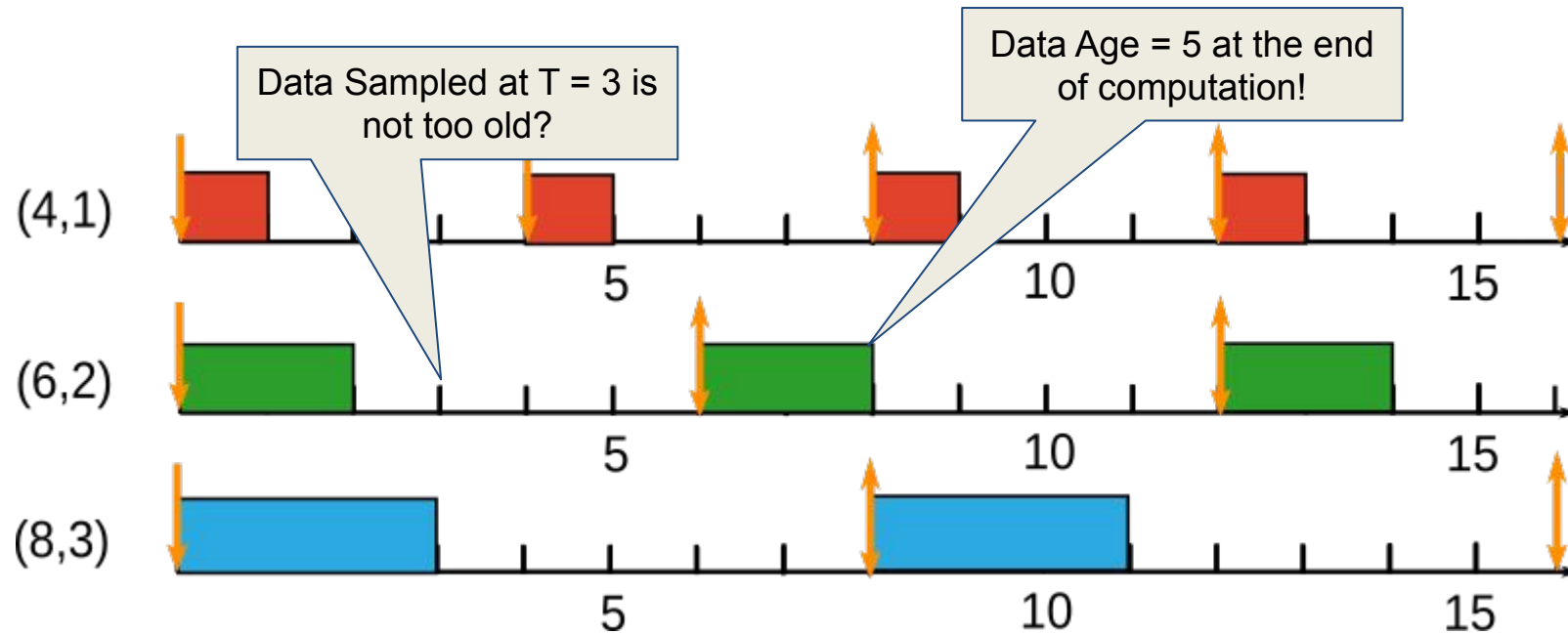
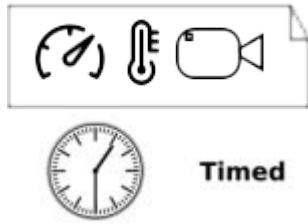
Data Sampled at  $T = -1?$



# What is lacking from classical RT Theory?

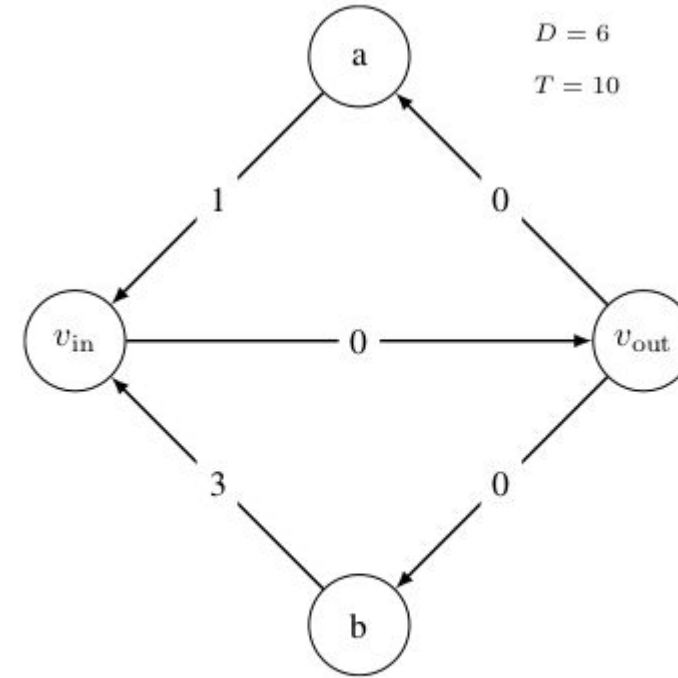
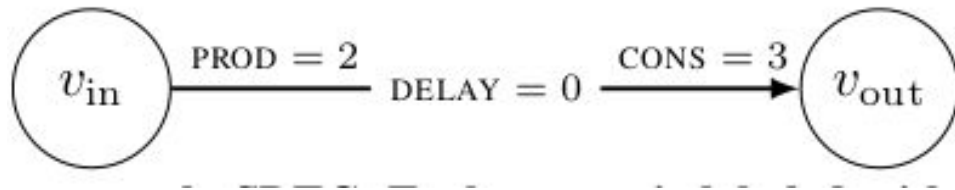
Contention?

Data?



# SDFG (Lee et al., 1987)

- Period, Deadlines, and WCET + Data dependency

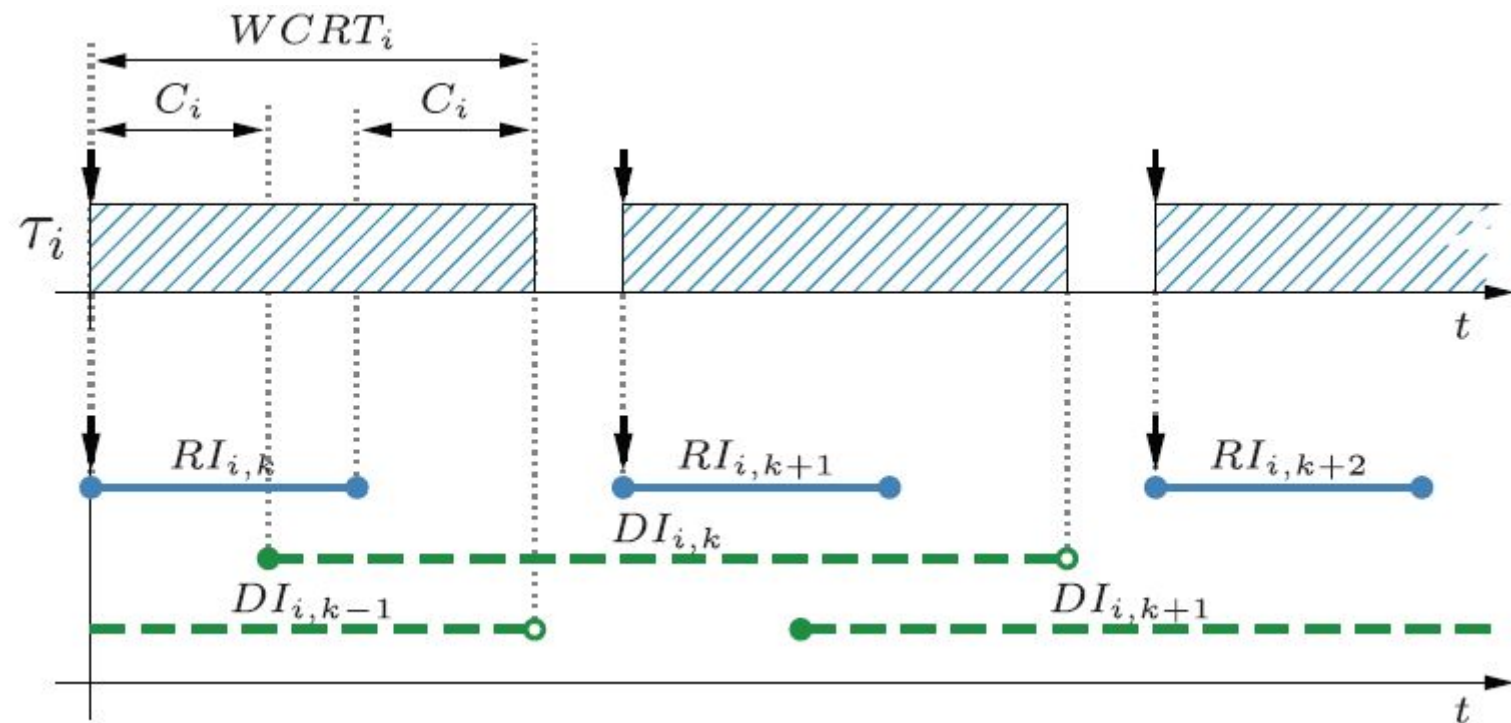


actor	$v_{in}$	$v_{out}$	$a$	$b$
WCET	1	1	1	2

- Throughput and energy constraints (Damavandpeyma et al., 2013), (Stuijk et al., 2007)
- Dynamic scheduling (Singh et al., 2017)
- Buffer estimation with unrolling techniques over task execution (Shin et al., 2010)
- Inspired Methodologies
  - e.g., Data communication

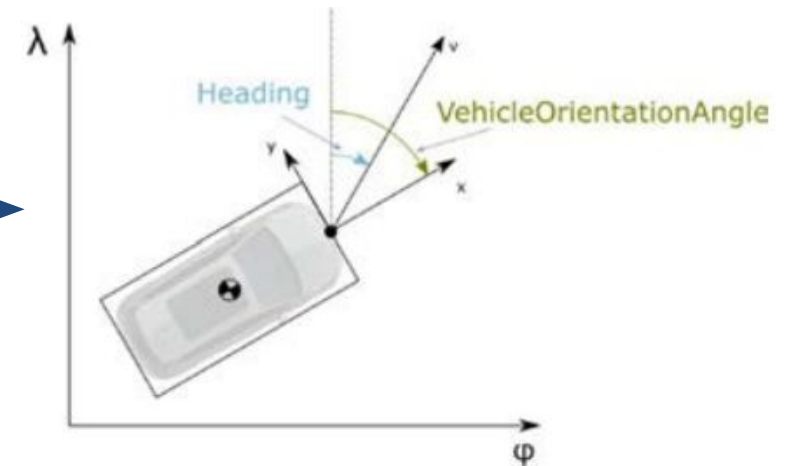
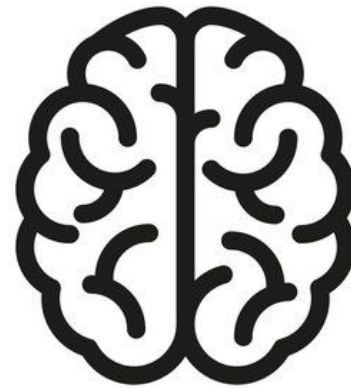
# End-to-end timing analysis (Becker et al. 2017)

- Task dependency, Cause-effect chains, End-to-End timing, and Data Age Constraint
  - Data propagates through a chain of tasks within certain time bounds.
    - Time from reading the data until the actuation is subject to delay constraints in addition to the task's individual timing constraints
- **Dynamic schedules** → WCRT (earliest and latest moment a task can run)
  - $C_i$  : WCET
  - $R_i$  : Read Interval
  - $D_i$  : Data Interval



- **What is lacking?**
  - Maximum Age:
    - What about data sampling rate?
  - Everything is at shared memory!
  - Semantics of data?

# What is lacking from classical RT Theory?

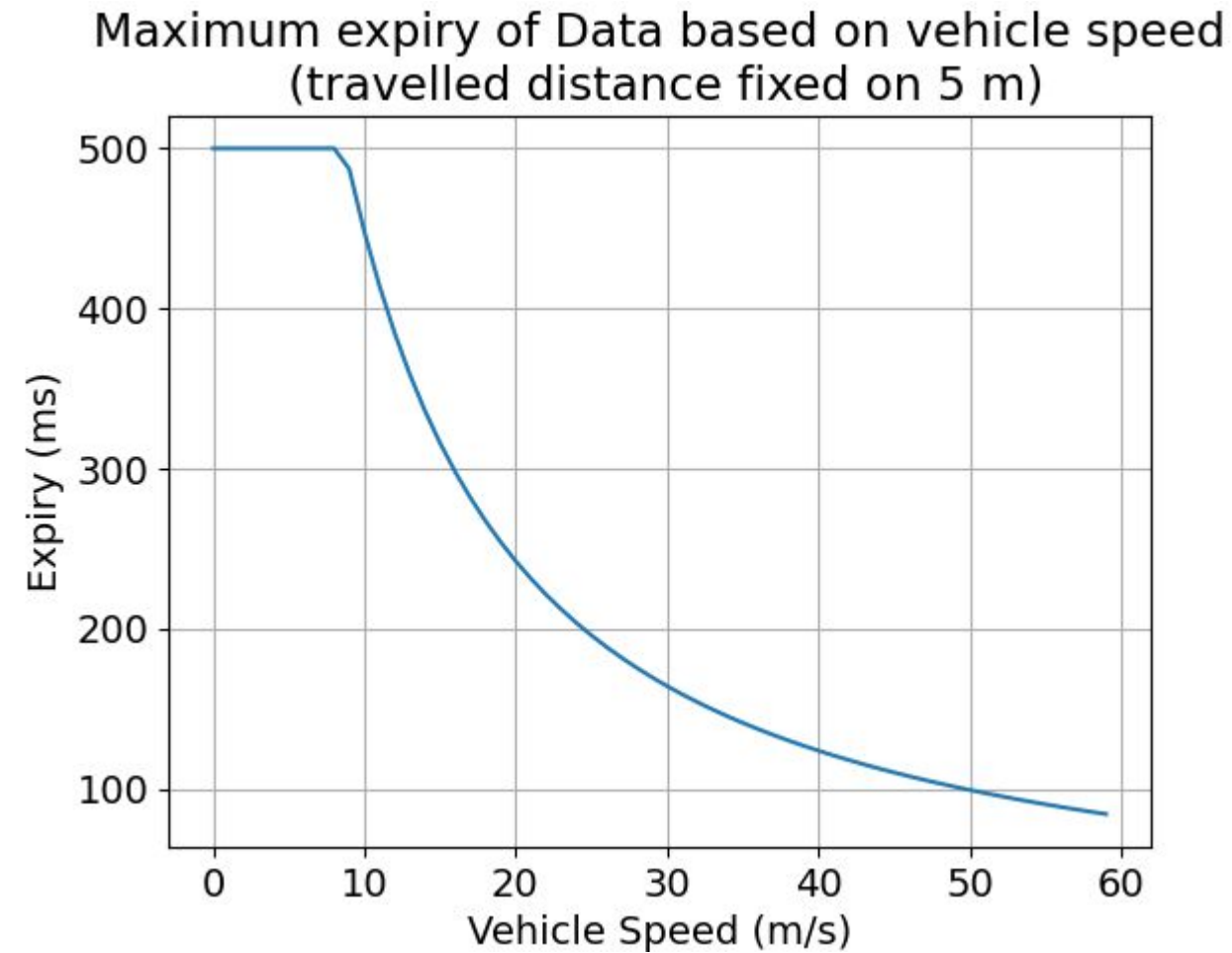


When?

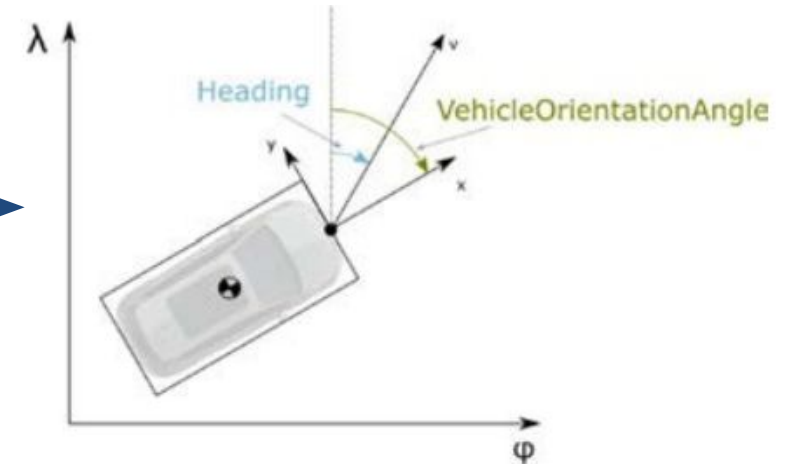
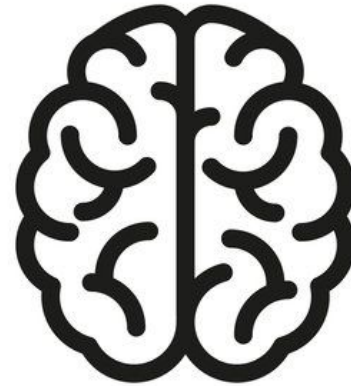
For those using this in next steps:  
is it valid until?

**Determined by the state of the system!**

# Update rate based on how much I have travelled



# What is lacking from classical RT Theory?



When?

For those using this in next steps:  
is it valid until?

**Dynamicity in time requirements?!**



# What is lacking from classical RT Theory?

- Errors on sensor!

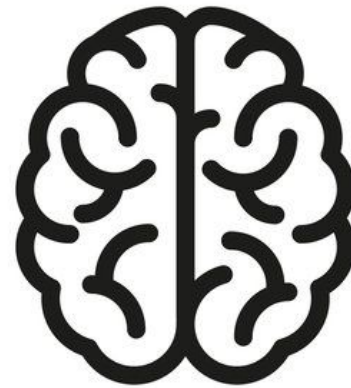


No vehicles ahead...  
No need to brake!

Plausible?

# What is lacking from classical RT Theory?

- Errors on AI!



Plausible?

No vehicles ahead...  
No need to brake!

# What is lacking from classical RT Theory?

Contention?

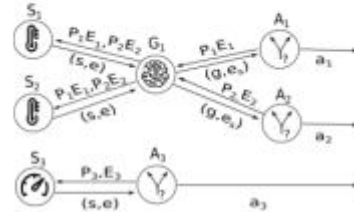


Data?

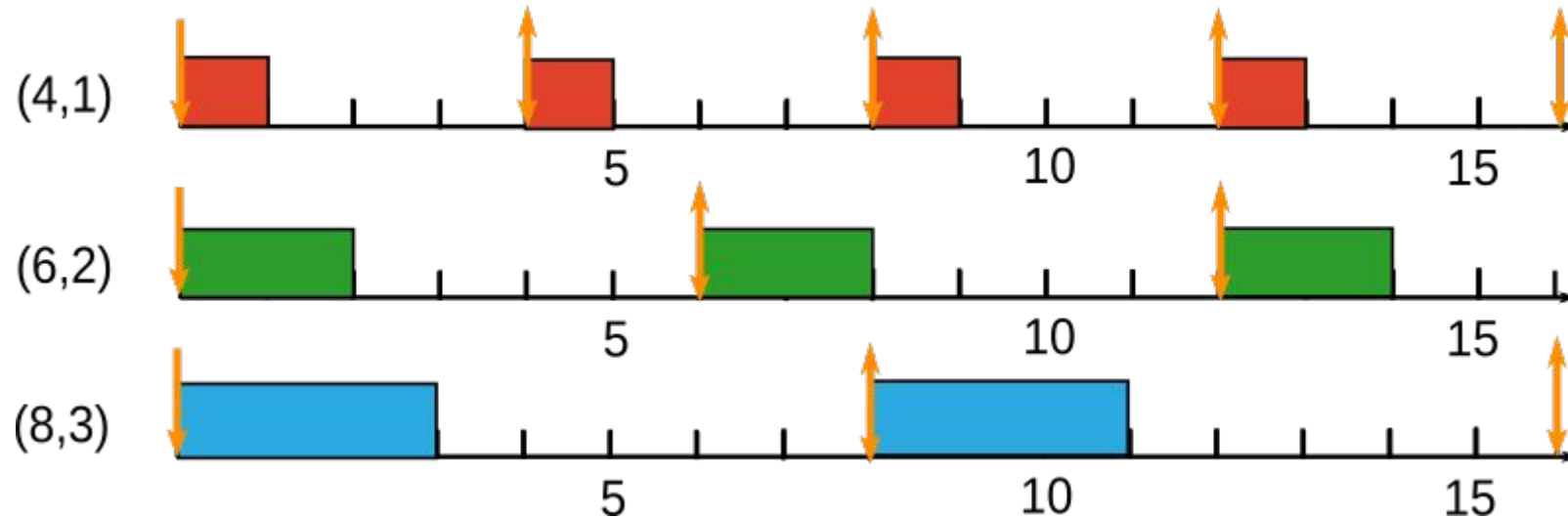


Timed

Network?



- Not everything is local!
  - shared memory assumption
- Random Delays!
  - Modeling Medium
- Wireless communication
  - Collision, hidden nodes...
- Safety-Critical: **Jitter and Latency!**



# What is lacking from classical RT Theory?

Contention?

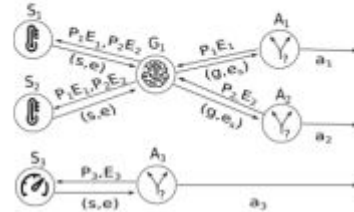


Data?

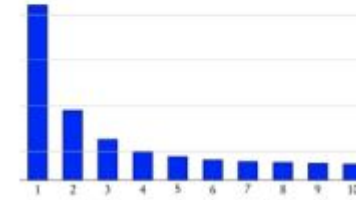


Timed

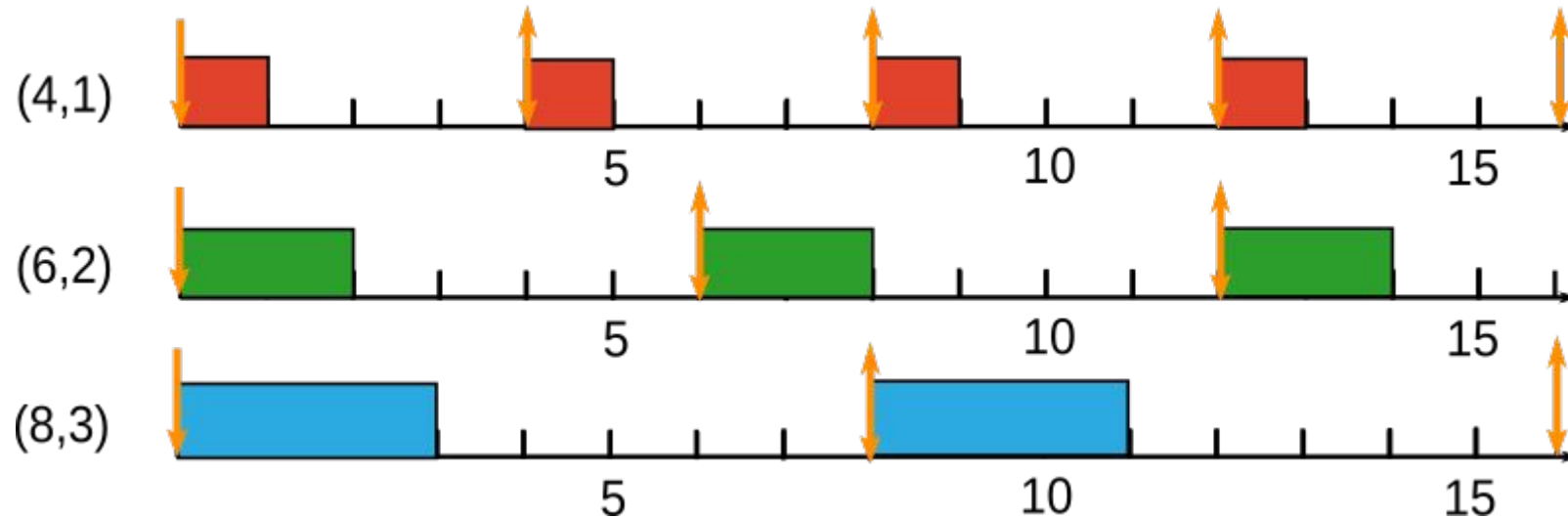
Network?



Bandwidth?



- Data flow... GB/s to TB/s
- **Safety-Critical:**
  - Fits in memory?
  - Fits in network?
  - Will it be there when needed?



# Contention in IoT Applications (Alexander and Stefano, 2023)

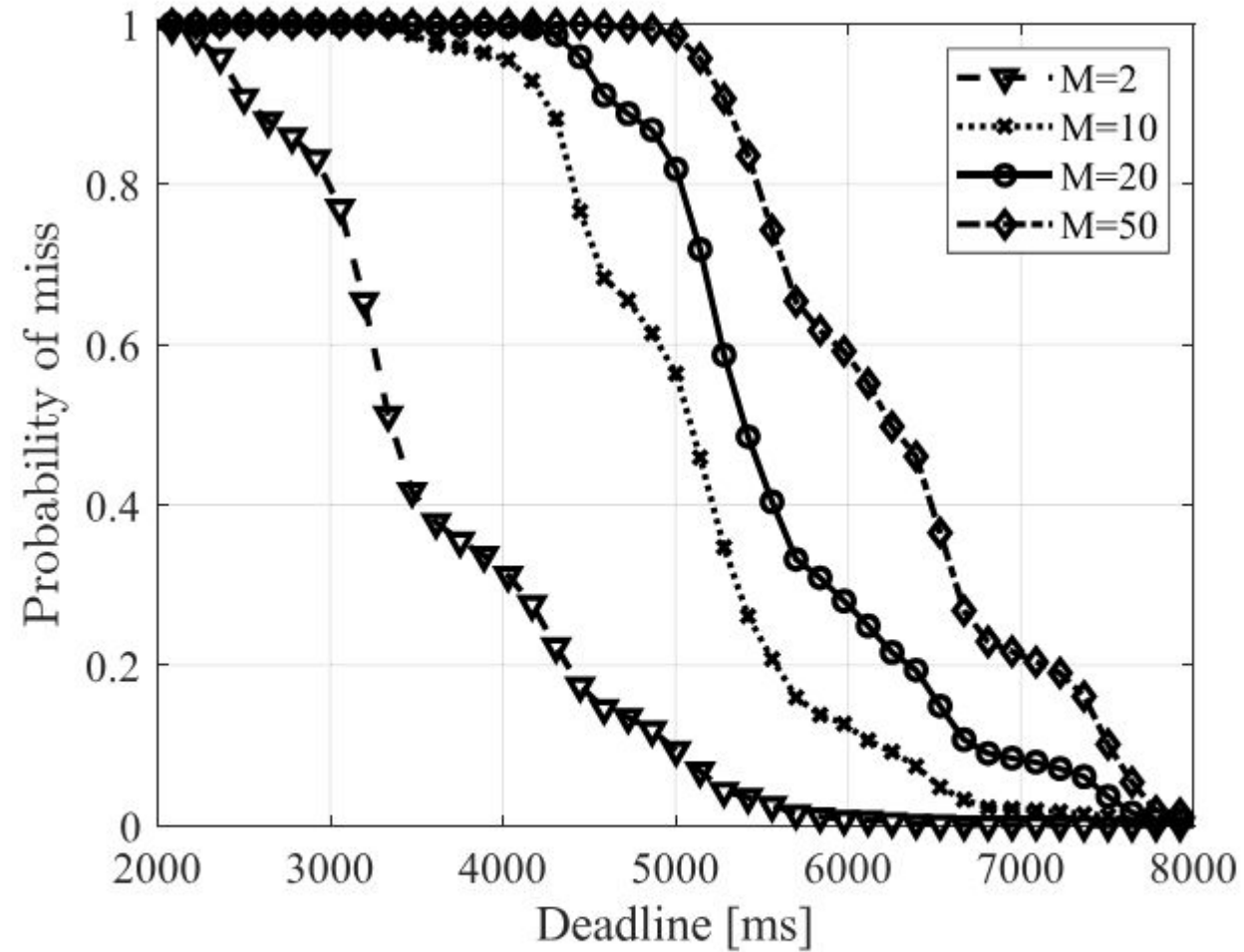
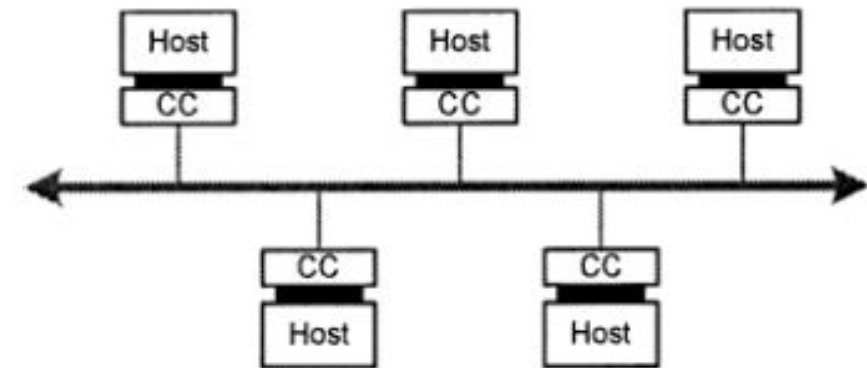
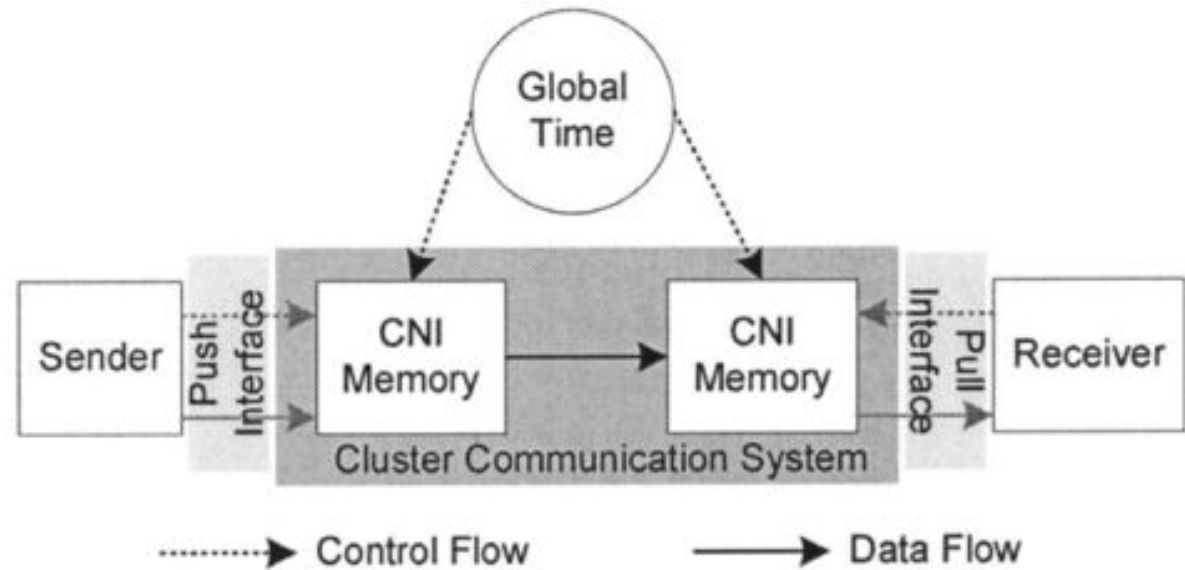


Fig. 7. Miss of deadline for a scenario of  $M$  smart sound sensors connected to one server. The GRS algorithm with  $I = 1000$  iterations.

# Time-Triggered Architecture (TTA) (Kopetz et al., 2003)

- Tasks, Interfaces, Nodes
  - Real-Time
    - Periods, Deadlines, WCET
- **Static Scheduling (TDMA)**
  - A priori send and receive times
- **Guardians**
  - Communication controllers
- TTW – (Jacob et al., 2020)
  - Protocol for Online Switch Mode
    - Pre-Computed Schedules (modes)

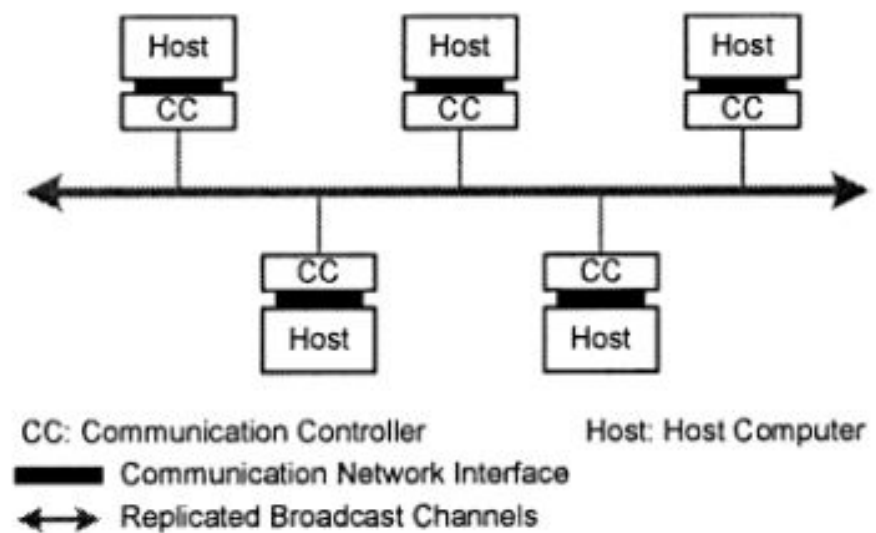
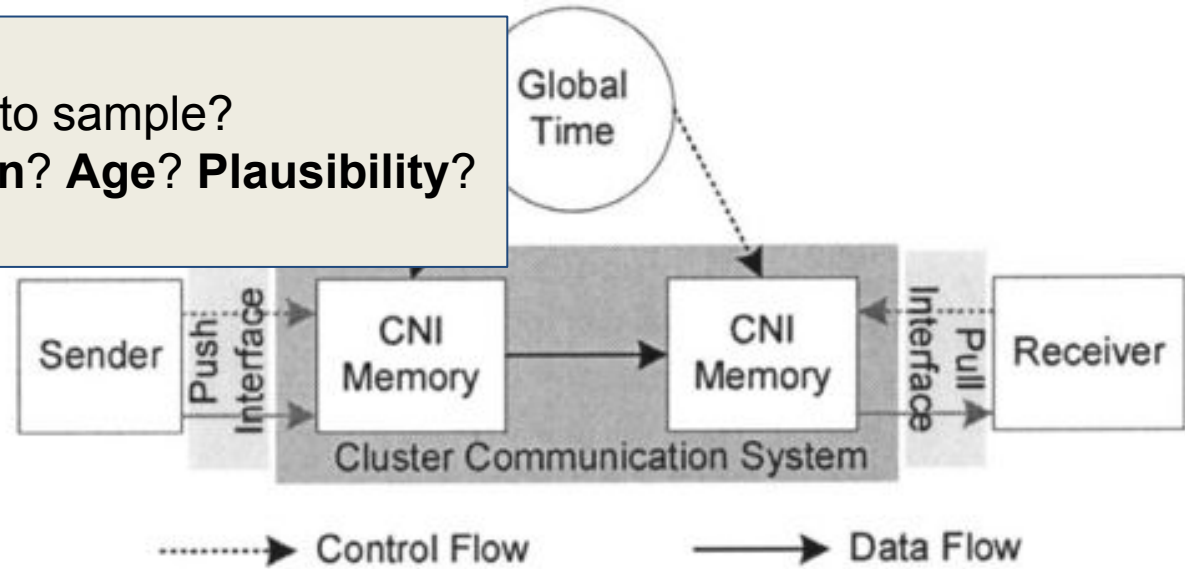


CC: Communication Controller      Host: Host Computer  
 ─── Communication Network Interface  
 ↔ Replicated Broadcast Channels

# Time-Triggered Architecture (TTA) (Kopetz et al., 2003)

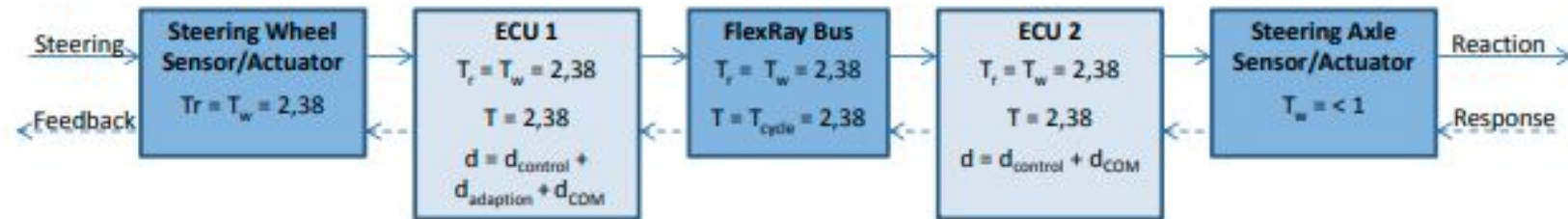
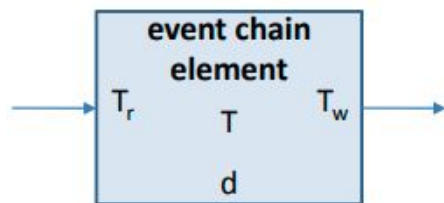
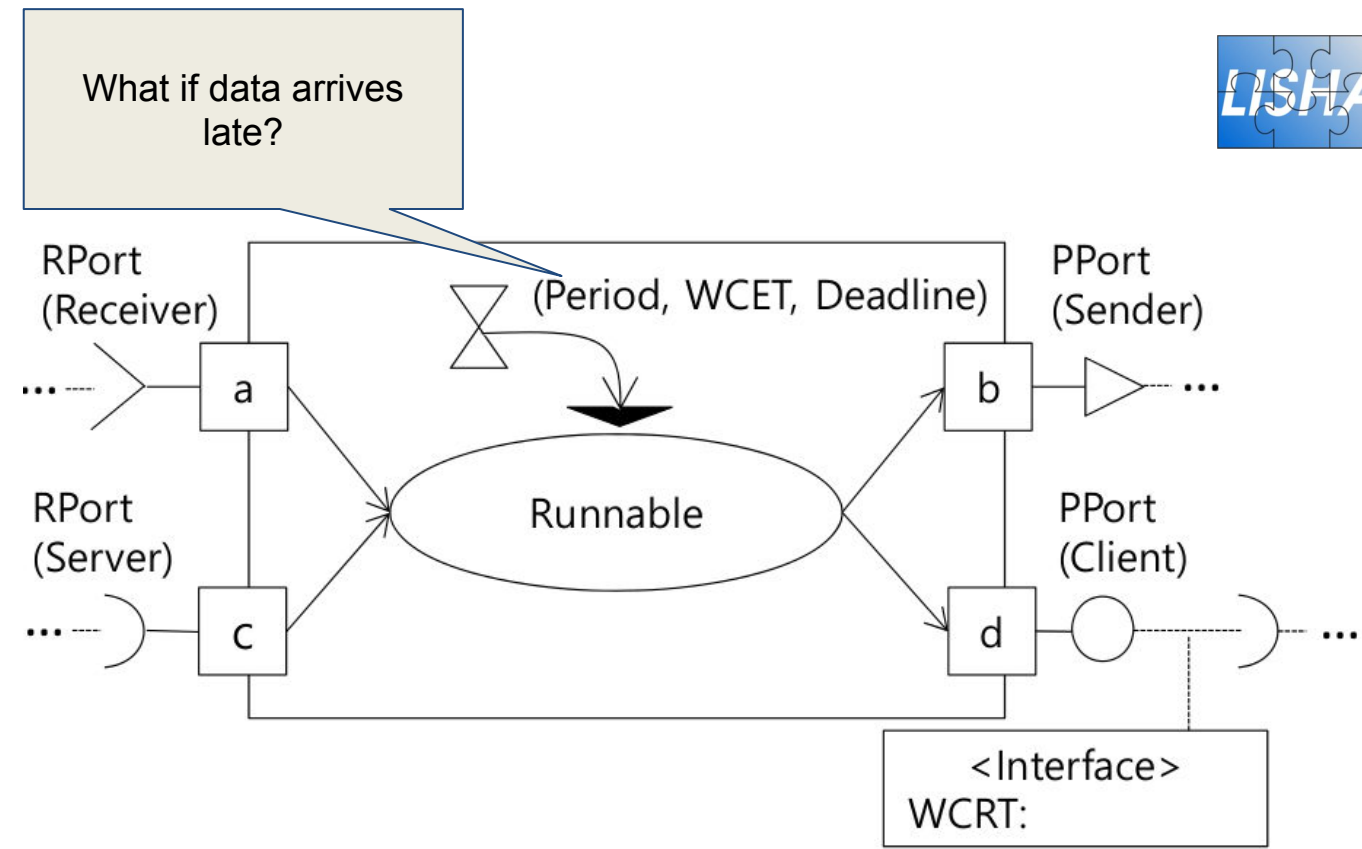
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- TTW – (Jacob et al., 2020)
  - Protocol for Online Switch Mode
    - Pre-Computed Schedules (modes)

How early do we need to sample?  
**Freshness? Expiration? Age? Plausibility?**



# AUTOSAR Design Overview

- Open standard for automotive Electrics/Electronics
  - Layered architecture description
    - **Components, Ports, and Interfaces**
    - **Decoupling of the functionality** from the supporting hardware and software services
  - Runtables
    - **Timing:** computation + communications
      - Period, Deadline, WCET, WCRT...
    - **Client-Server:** Operations that can be invoked by components
    - **Sender-Receiver:** interface supports the data communication



(Klobedanz et al., 2010) and (Kim et al., 2016)



# What is lacking from classical RT Theory?

Contention?

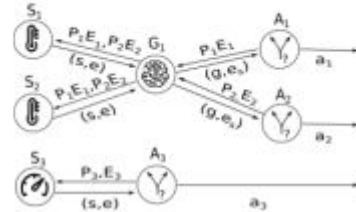


Data?

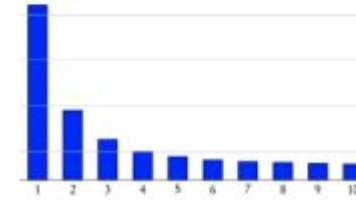


Timed

Network?



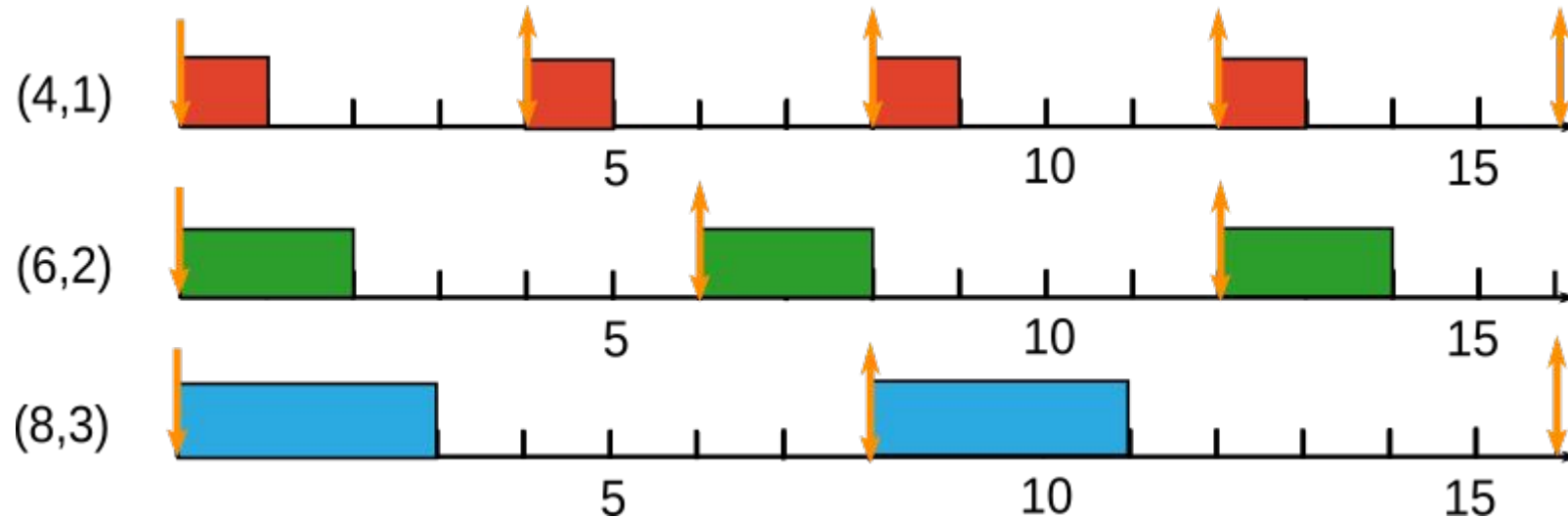
Bandwidth?



Security?



- Not everything is isolated...
- **Safety-Critical:**
  - What is safe?
  - Which algorithm?
  - How long does it take to decrypt?
  - Communication Protocol Steps
    - Key update?
    - Interruptions
    - etc.



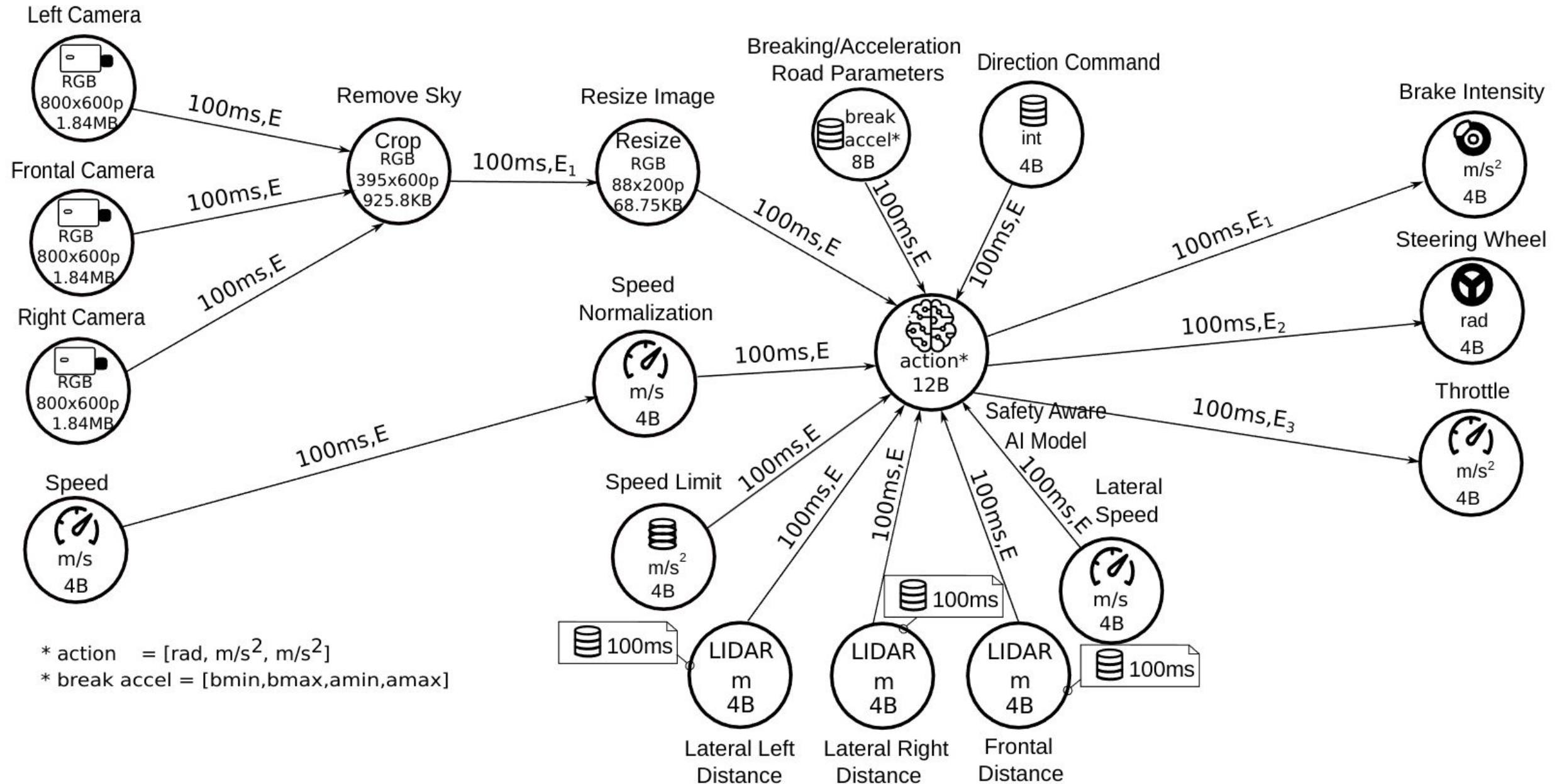
# Open Problems

- How to combine RT-Theory with novel requirements of data, security, dependency, etc...
  - Data-Centric Design

# Period and Expiry

- **Period** = The period to which data must be sampled!
- **Expiry** = The last moment in time a data can be considered valid!
- A valid data shall always be available in the system:
  - Sampling =  $\min(P, E)$
- In Network
  - **Priority**: sending data closer to being expired
  - **Optimization**: Discard data that will not reach destination in time
- In computation element
  - S1 uses S2 and S3 to produce a new sample s1
  - P = The period a new data must be produced (s1)
  - E = The last moment in time an input can be considered valid
  - $\rightarrow E = \min(s2.E, s3.E)$
  - e.g., P = 100 and E = 100
    - Data can be computed any time during period
    - Expiry = Data produced at  $t = 10 \rightarrow$  computation must be finished until 100 (Period)
    - New data produced at  $t = 90 \rightarrow$  Next computation must be finished until 190 (Expiry)
  - Why 10 and 90?  $\rightarrow$  communication delays, re-sampling due to error or low confidence data, etc.

# Interest Relationship



# Schedulability

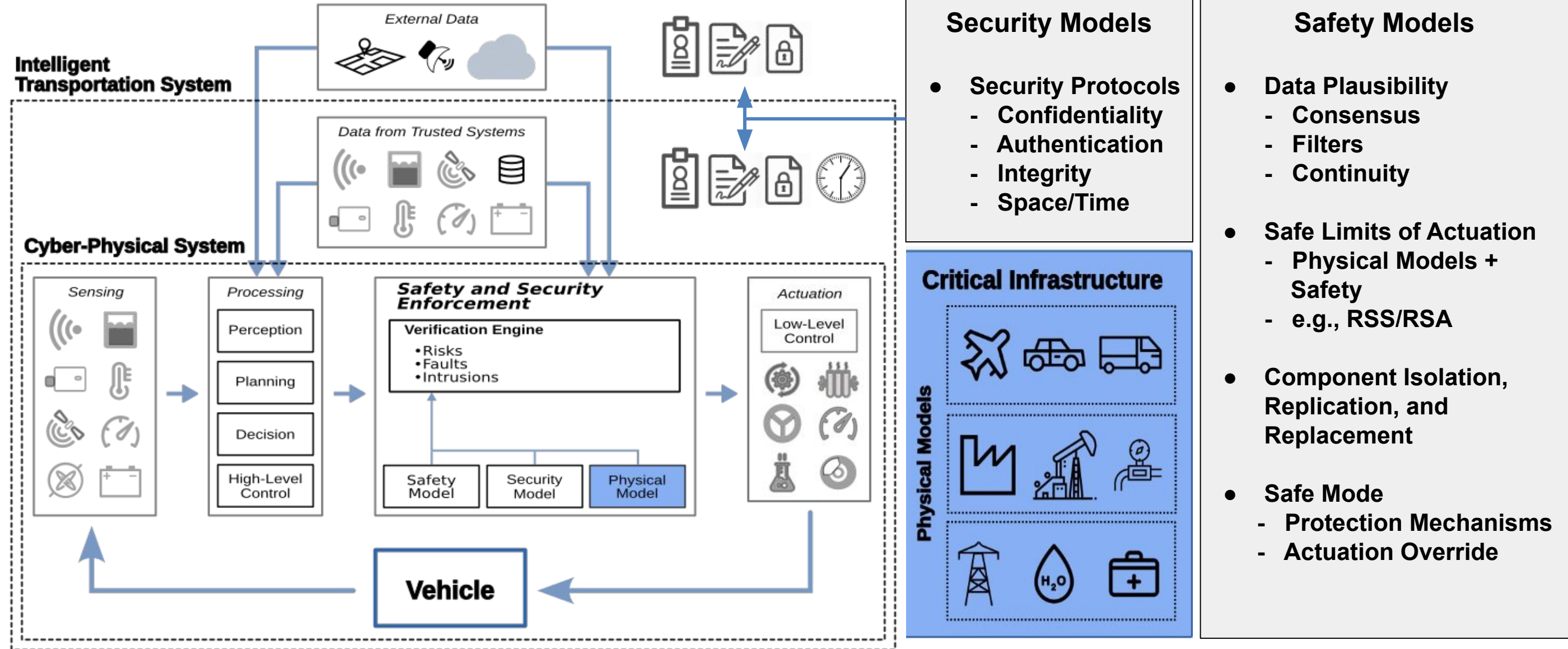
- Estimated Costs
  - Data **bandwidth**: **Data Type** and How data is expected to be produced (period, expiry, how many samples per period, etc.)
  - **Account for security in latency**
  - **Schedulability**: Network model (1 sink vs. N sinks), **Protocol**, bandwidth, topology, expiry, latency **and jitters, fault tolerance**
    - Huegel et al., **procedure Analyze** ( $\mathcal{I}, \mathcal{N}, MOS, M_{rate}, t_{mac}$ )
      - $\mathcal{I}' \leftarrow \mathcal{I}$  ordered by  $\min(i.period, i.expiry)$  ascendant, where  $i \in \mathcal{I}$
      - $\mathcal{N}' \leftarrow \mathcal{N}$  ordered by  $hops(n, sink)$  descendent, where  $n \in \mathcal{N}$
  - **Local Scheduling**: **Capacity of multiple resources, Expiry, and WCET** of updates
    - **Local Bandwidth and Memory reservation**: **Expiry, Period, latency, bandwidth**
  -

# Open Problems

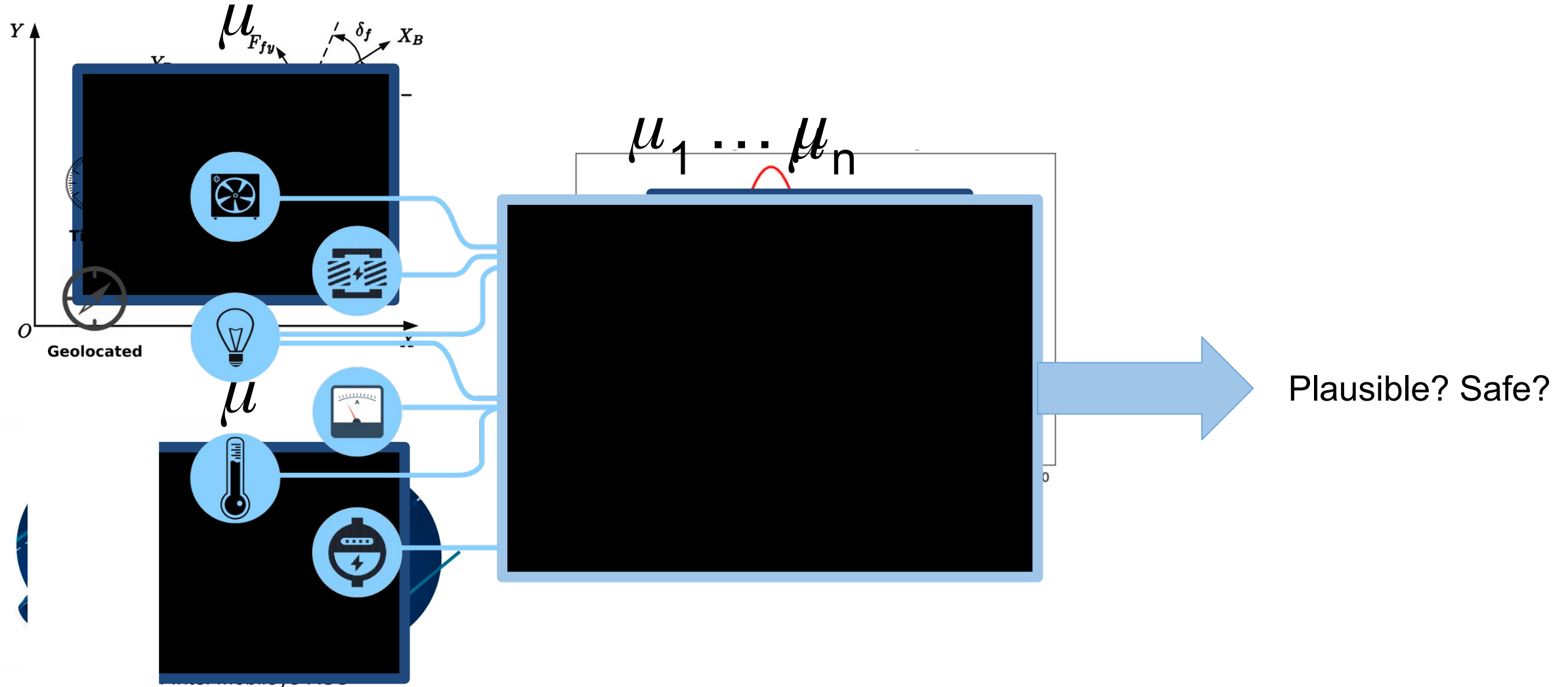
- How to combine RT Theory with novel requirements of data, safety, dependency, and timing
  - Data-Centric Design
- What about safety properties?
  - Formal methods automatically derived from the design

# Data-Driven Cyber-Physical System Safety

Cloud



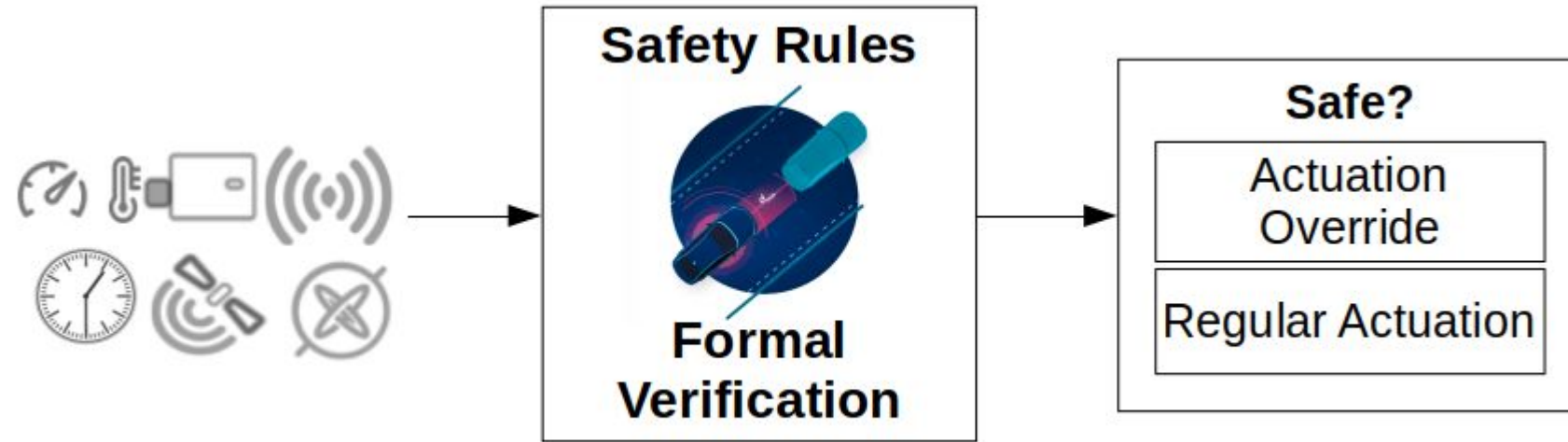
# Plausibility Verification → Keep it Simple!





# Run-Time Verification

- Formal Logic: Signal Temporal Logic



$$\varphi_{S_k} \models \bigwedge_{j=0}^{|S_k \cdot I|} (\varphi_{S_j} U_{[0, i_{S_k, S_j} \cdot e]} \mu(s_k))$$

$$SEU.I = i(SEU, S_k) \forall S_k \in S.O \cup S.\bar{I} \cup S.T.$$

$$\varphi_{SEU_j} \models \diamond_{[0, P_j]} \varphi_{S_j}$$

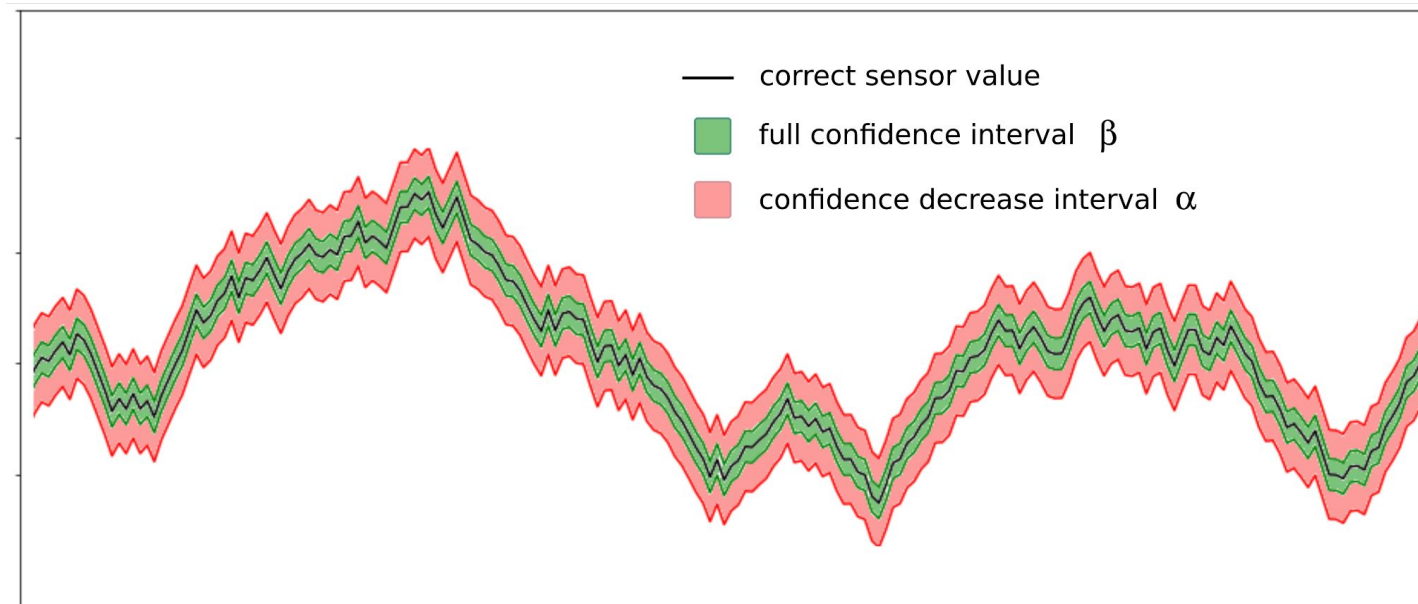
- Automatic code generation!
  - U for each interest and (eventually for each data and phase of security protocol)

# Open Problems

- How to combine RT Theory with novel requirements of data, safety, dependency, and timing
- What about safety properties?
- Sensor Plausibility

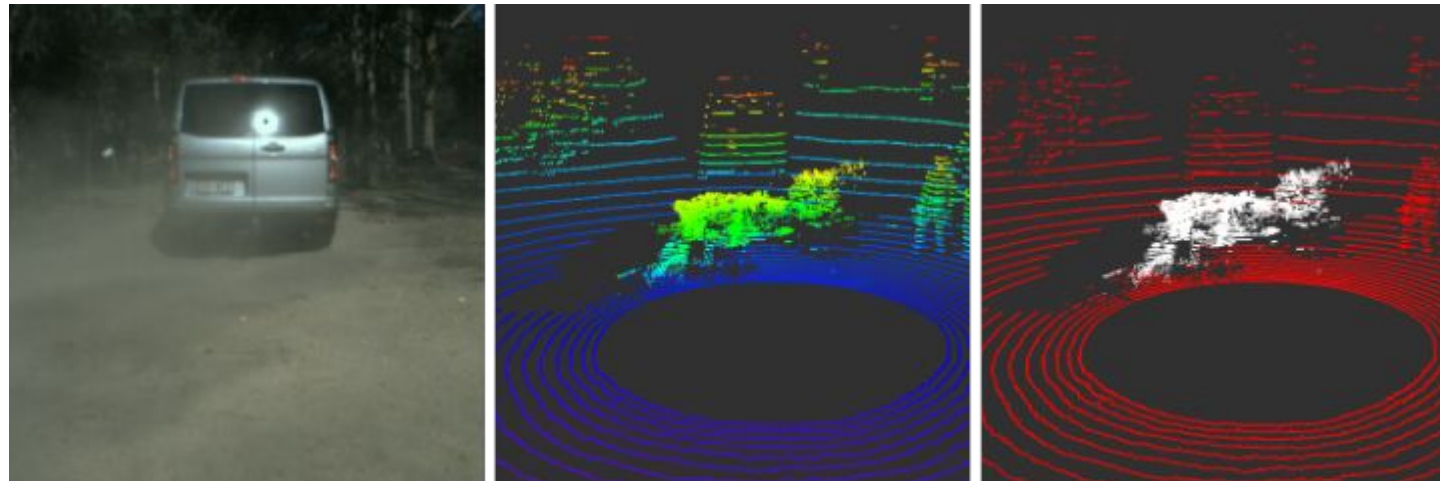
# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
- What about safety properties?
- Sensor Plausibility
  - Confidence (Scheffel et al., 2018)
    - Predict data: AI + Data Correlation OR based on a physical model (e.g., CTRV)
    - Compare to real reading and check difference according to threshold (data-driven value)



# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
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- Sensor Plausibility
  - Confidence (Scheffel et al., 2018)
    - Predict data: AI + Data Correlation OR based on a physical model (e.g., CTRV)
    - Compare to real reading and check difference according to threshold (data-driven value)
  - Specific Sensor approaches
    - Data Filtering, Kalman filters, Time-series (how much changed?)

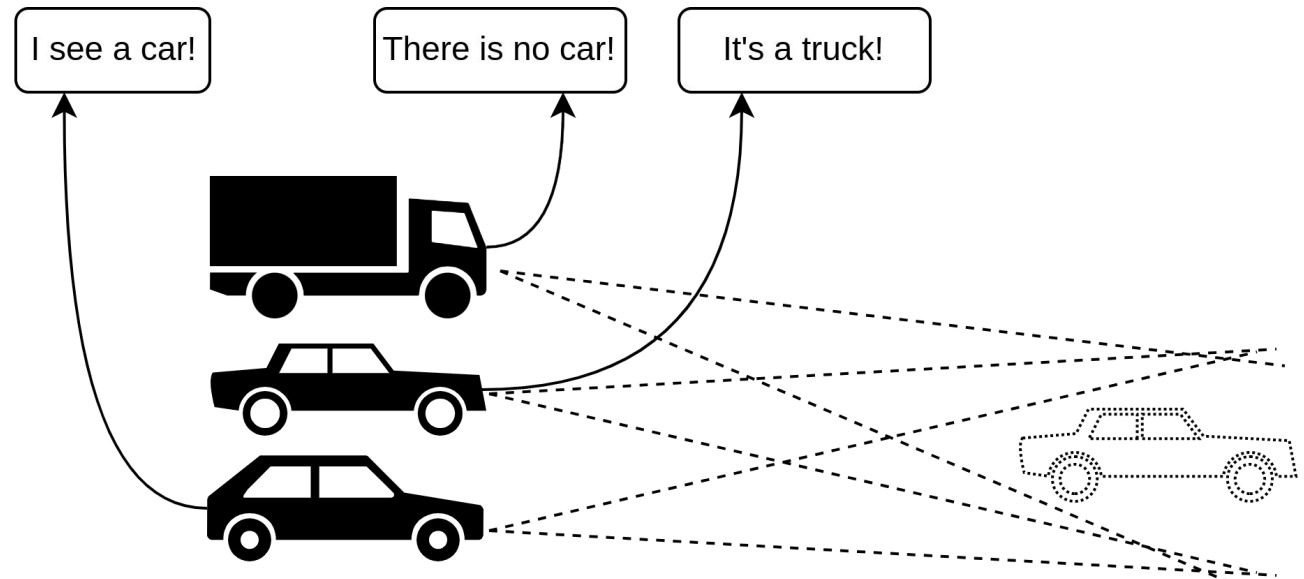
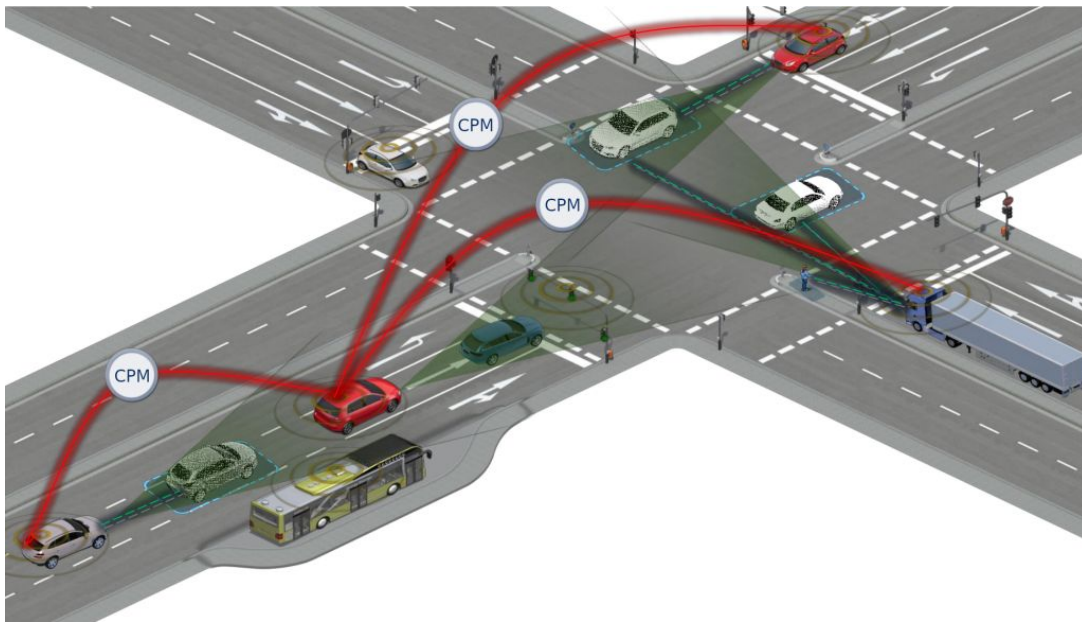


Source: Stanislas et al., 2021

- Trigger re-sampling
  - Do we still have time?

# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
- What about safety properties?
- Sensor Plausibility
  - Confidence (Scheffel et al., 2018)
  - Specific Sensor approaches
  - Cooperative perception (V2X)
    - ETSI standard



# Open Problems

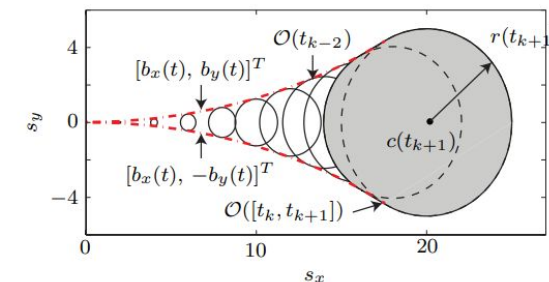
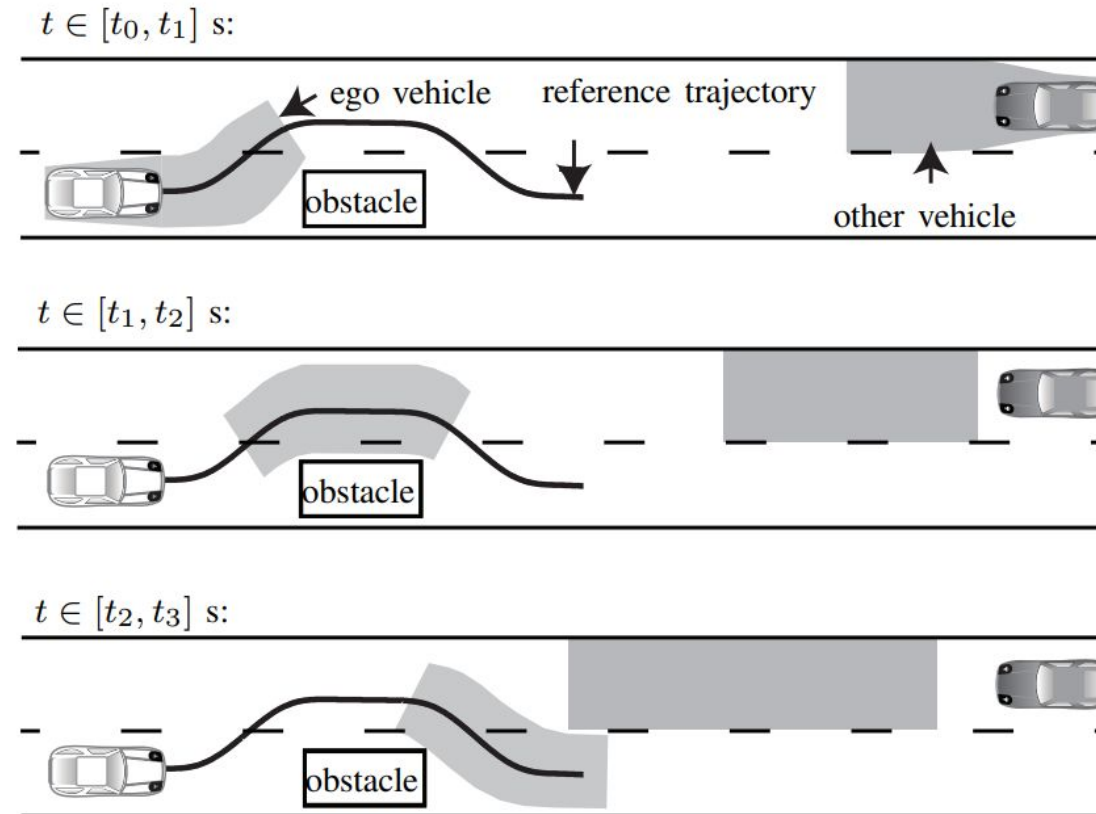
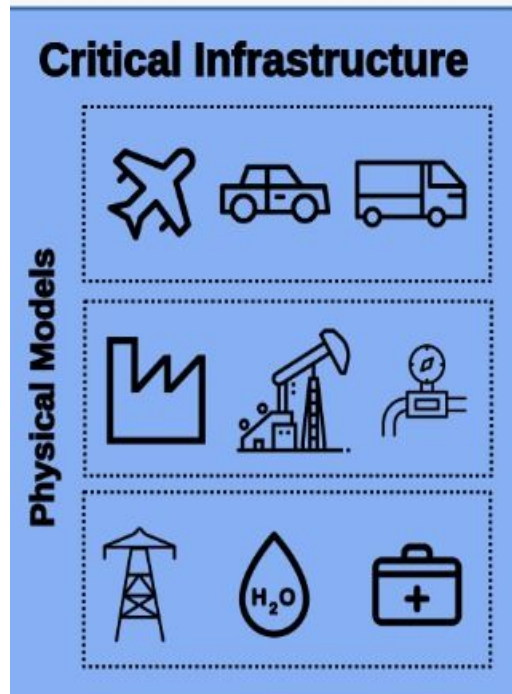
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# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
- What about safety properties?
- Sensor Plausibility
- AI Plausibility

# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
- What about safety properties?
- Sensor Plausibility
- AI Plausibility
  - Cooperative perception (V2X)
  - Confidence?
    - AI to check AI?
  - Physical and Safety Models



RSA by (Althoff et al. 2016)

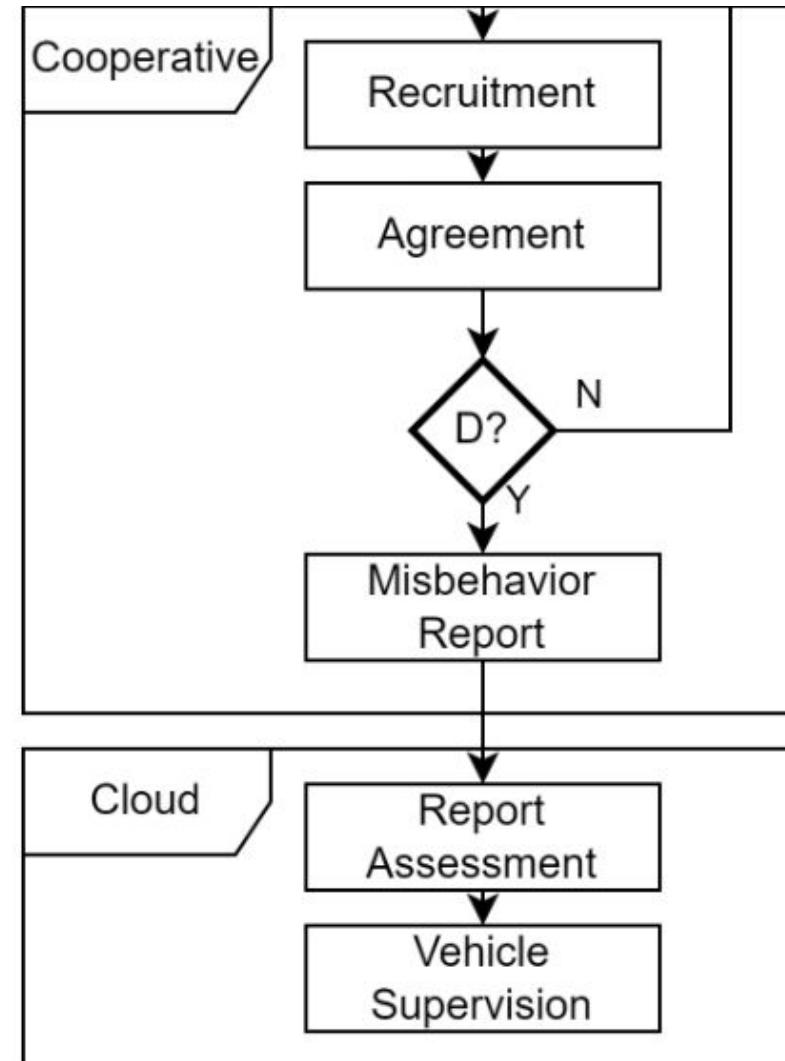


# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
- What about safety properties?
- Sensor Plausibility
- AI Plausibility
- Security

# Open Problems

- How to combine RT Theory with novel requirements of data, security, dependency, etc...
- What about safety properties?
- Sensor Plausibility
- AI Plausibility
- Security
  - Security Protocols
    - State Machine for Protocol
    - Based on Speed define:
      - Time to reach end of current group key  
→ Re-negotiation of keys
  - Data consensus
    - Misbehavior detection
      - Spreading of false data in V2X
      - (Lucena and Fröhlich, 2022)



# Timed Data: Are deadlines enough?

**Pesaresi Seminars - 2023**  
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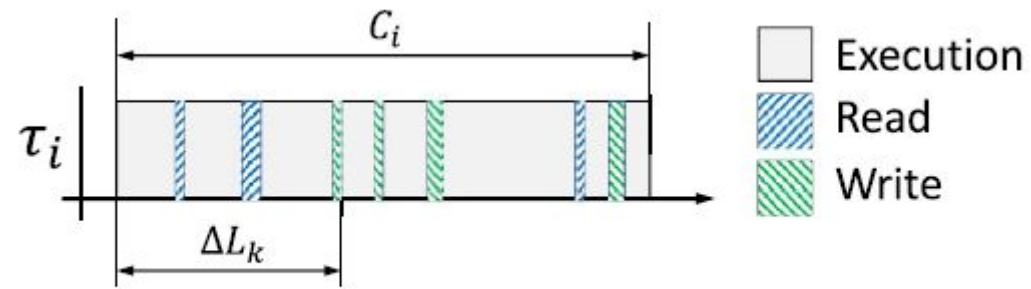
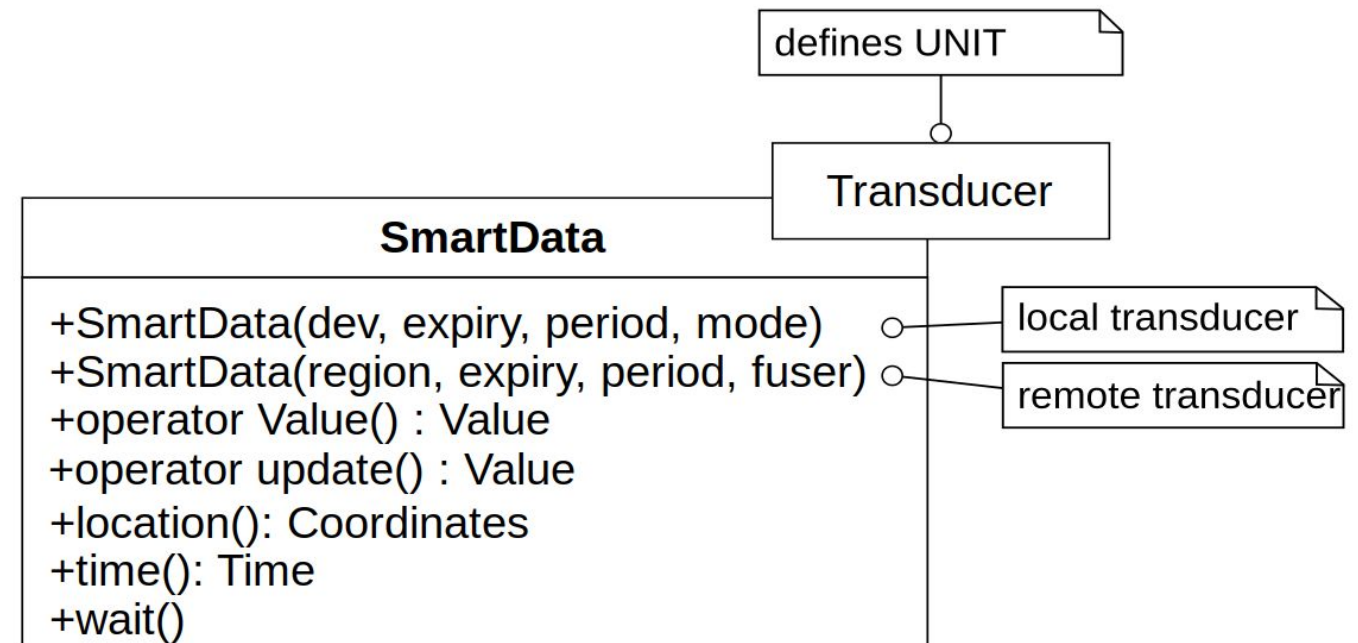


Fig. 8. Read and write operations in the explicit communication model.

# Data-Driven Design with SmartData

- “SmartData is a piece of data enriched with enough metadata to make it self-contained regarding semantics, spatial location, timing, and trustfulness”
  - Antônio Augusto Fröhlich, *SmartData: an IoT-Ready API for Sensor Networks*, In: International Journal of Sensor Networks, 28(3):202-210, 2018, [10.1504/IJSNET.2018.096264](https://doi.org/10.1504/IJSNET.2018.096264).
- Space-Time
  - Timing
  - Location
  - Mobile
- Semantics
  - Local
  - Remote
  - SI Physical Quantity and Carefully tailored Digital Units



# SmartData Interfaces

